

# **An HMM-Based Approach to Flexible Speech Synthesis**

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Keiichi Tokuda

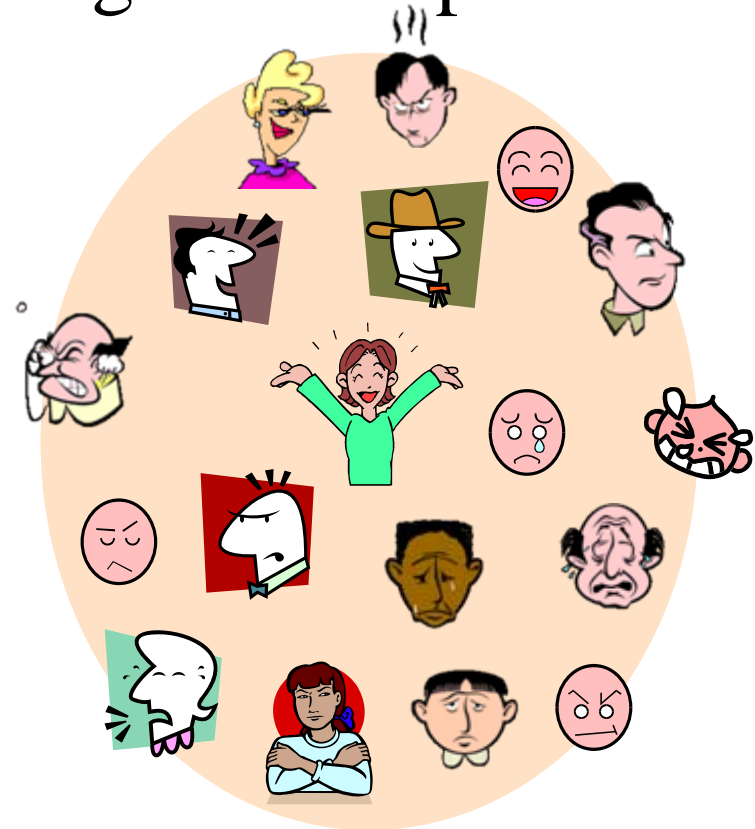
Nagoya Institute of Technology



# Towards Human-like Talking Machines

□ For realizing natural human-computer interaction, speech synthesis systems are required to have an ability to generate speech with:

- arbitrary speaker's voice
- various speaking styles
- emphasis
- emotional expressions
- and so on



# Corpus-Based Speech Synthesis

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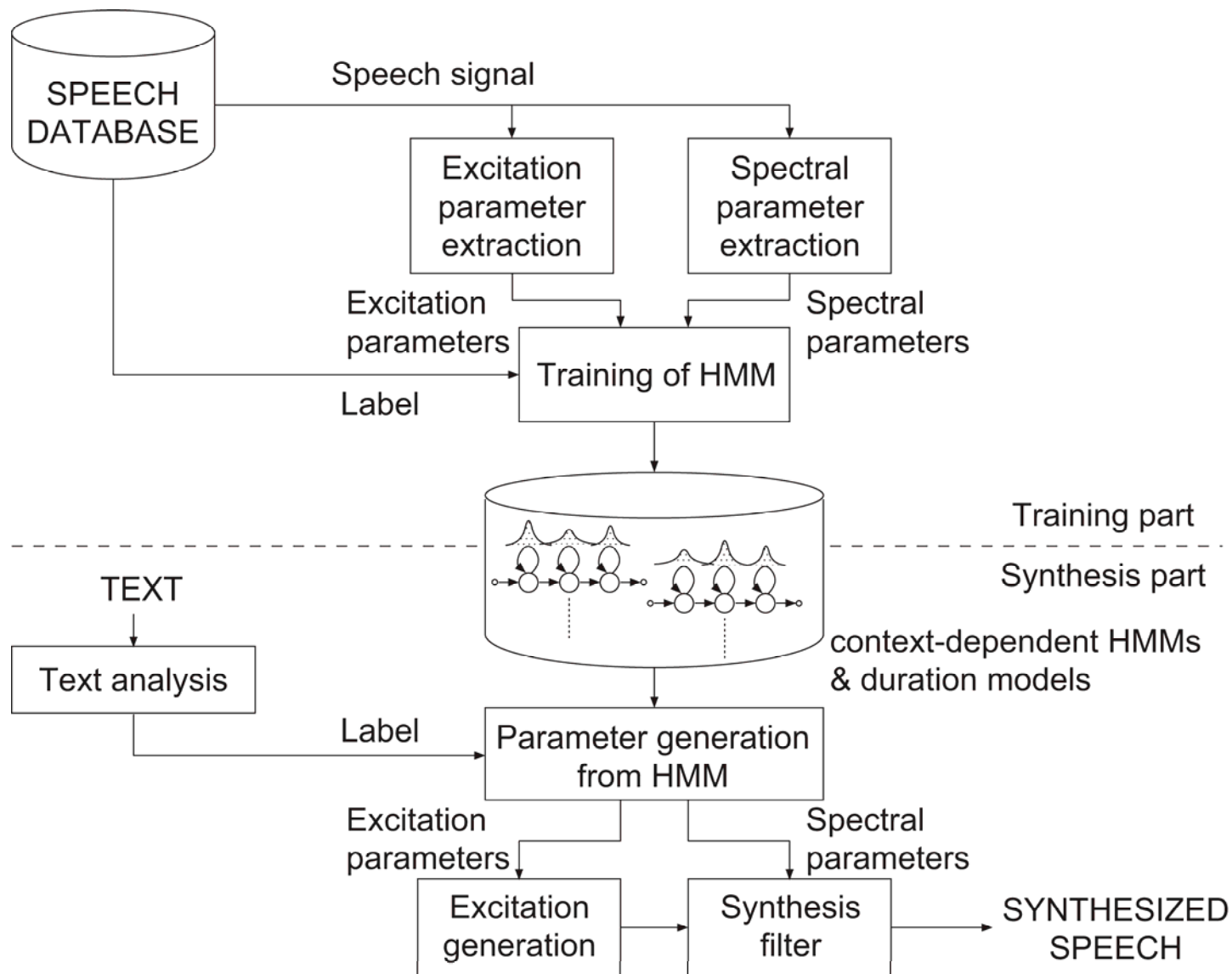
## □ **Unit selection approach**

- High quality speech can be synthesized using waveform concatenation algorithms.
- To obtain various voices, a large amount of speech data is necessary.

## □ **HMM-based approach**

- Generate speech parameters from statistics.
- Voice quality can easily be changed by transforming HMM parameters.

# System Overview



# Overview of This Talk

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- Basic Techniques
  - Vocoding technique
  - Speech Parameter generation algorithm
  - F0 pattern modeling
- Recent improvements and evaluation
- Relation to the unit selection approach
- Flexibility of the approach
  - Speaker adaptation (mimicking voices)
  - Speaker Interpolation (mixing voices)
  - Eigenvoices (producing voices), etc.

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## □ Basic Techniques

- Vocoding technique
- Speech Parameter generation algorithm
- F0 pattern modeling

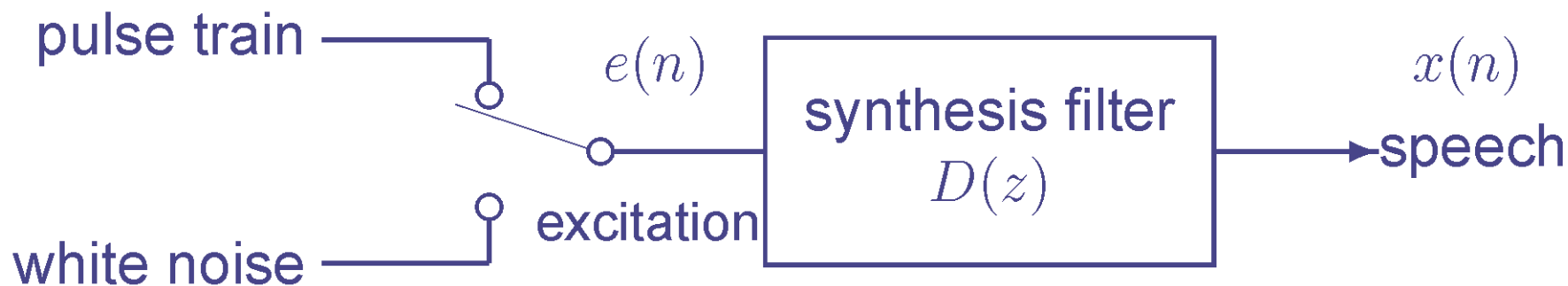
## □ Recent improvements and evaluation

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- Speaker adaptation (mimicking voices)
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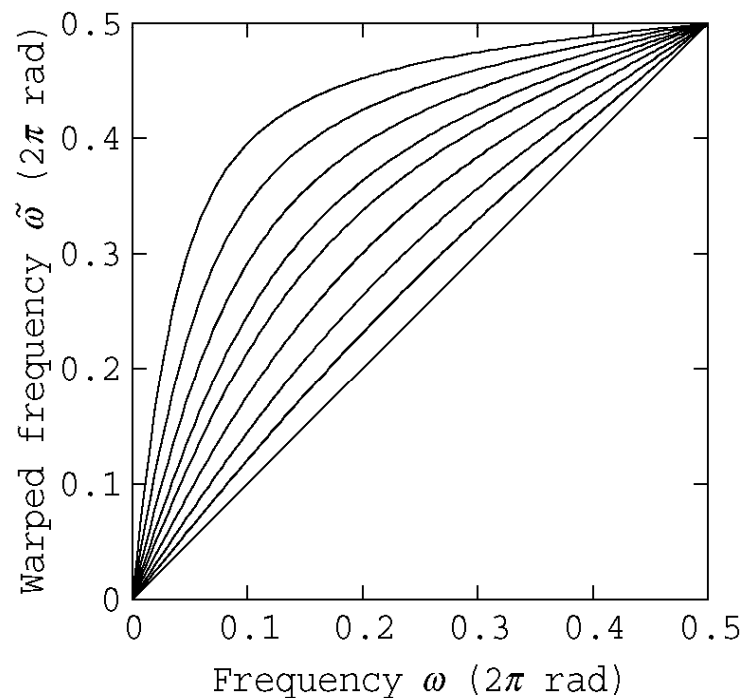
# Source-Filter Model



$D(z)$  should be defined by the state output vector of HMM, e.g., mel-cepstrum, lsp's

# Synthesis Filter Model

$$D(z) = \exp \sum_{m=0}^M c(m) \tilde{z}^{-m}, \quad \tilde{z}^{-1} = \left. \frac{z^{-1} - \alpha}{1 - \alpha z^{-1}} \right|_{z=e^{-j\omega}} = e^{-j\tilde{\omega}}$$



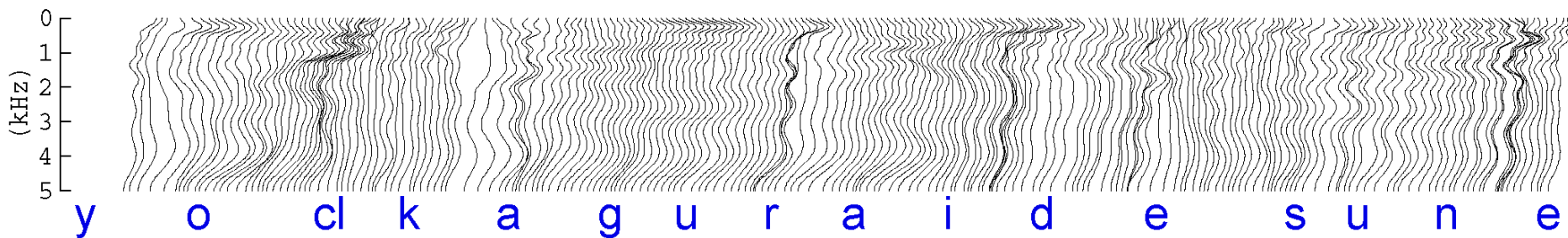


# Objective Function

$$\mathbf{c} = \arg \max_{\mathbf{c}} P(\mathbf{x} | \mathbf{c})$$

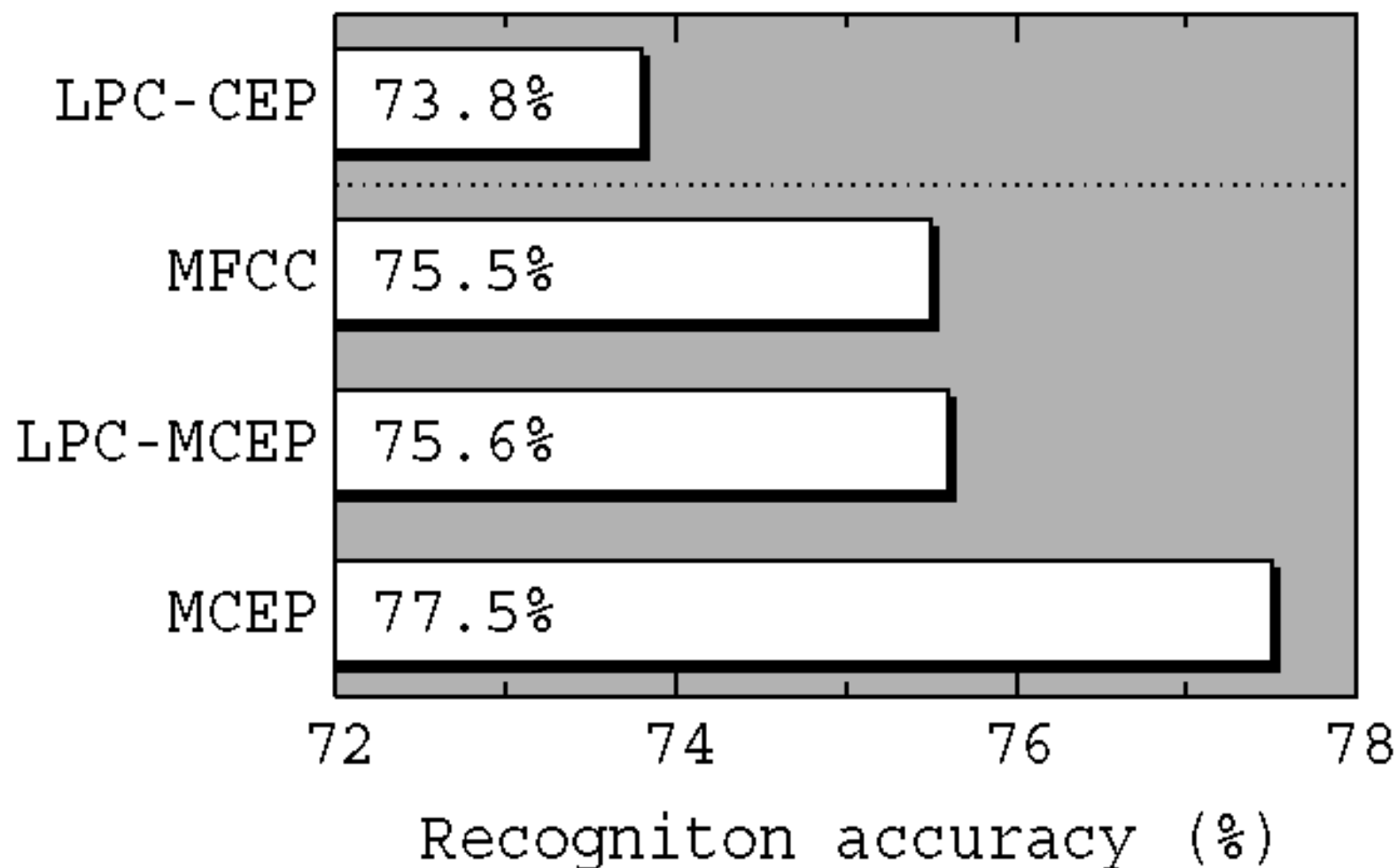
$$\mathbf{x} = [x(0), x(1), \dots, x(N-1)]'$$

$$\mathbf{c} = [c(0), c(1), \dots, c(M)]'$$



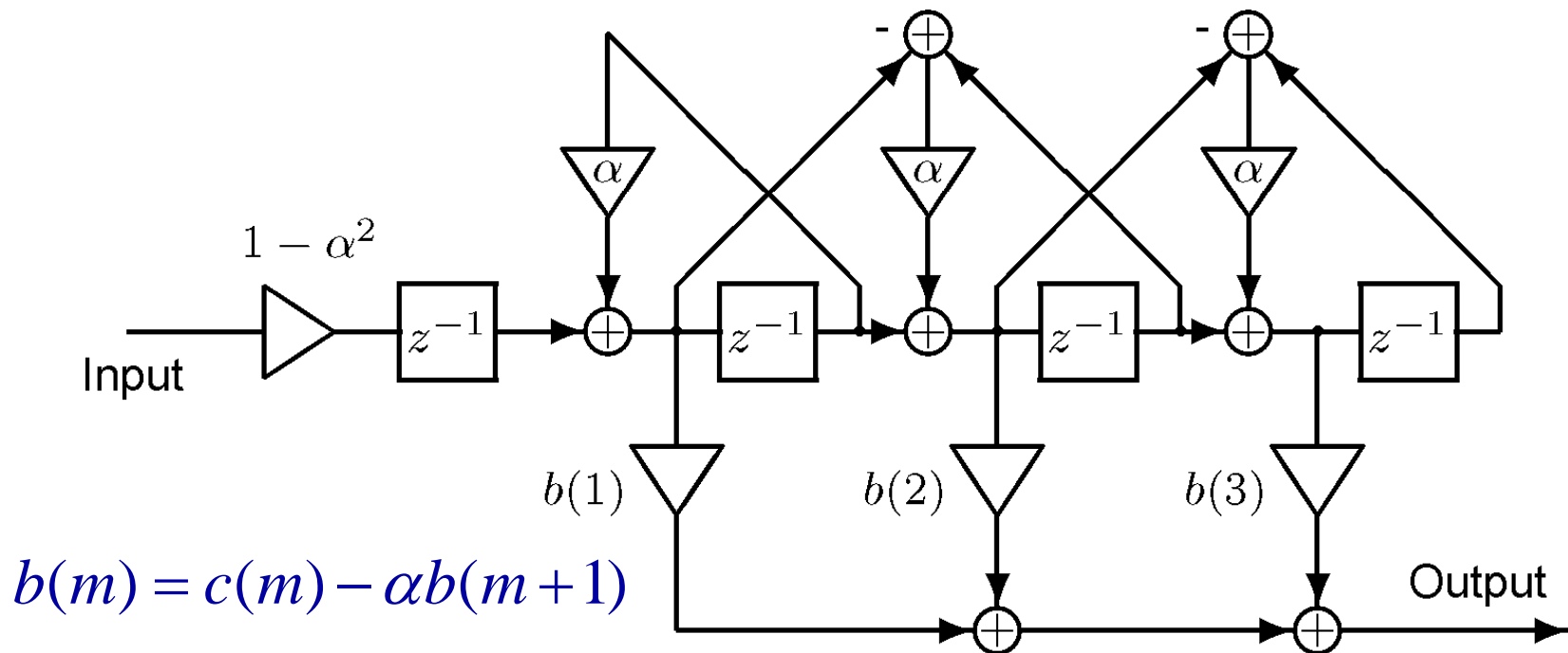
# Evaluation in Speech Recognition

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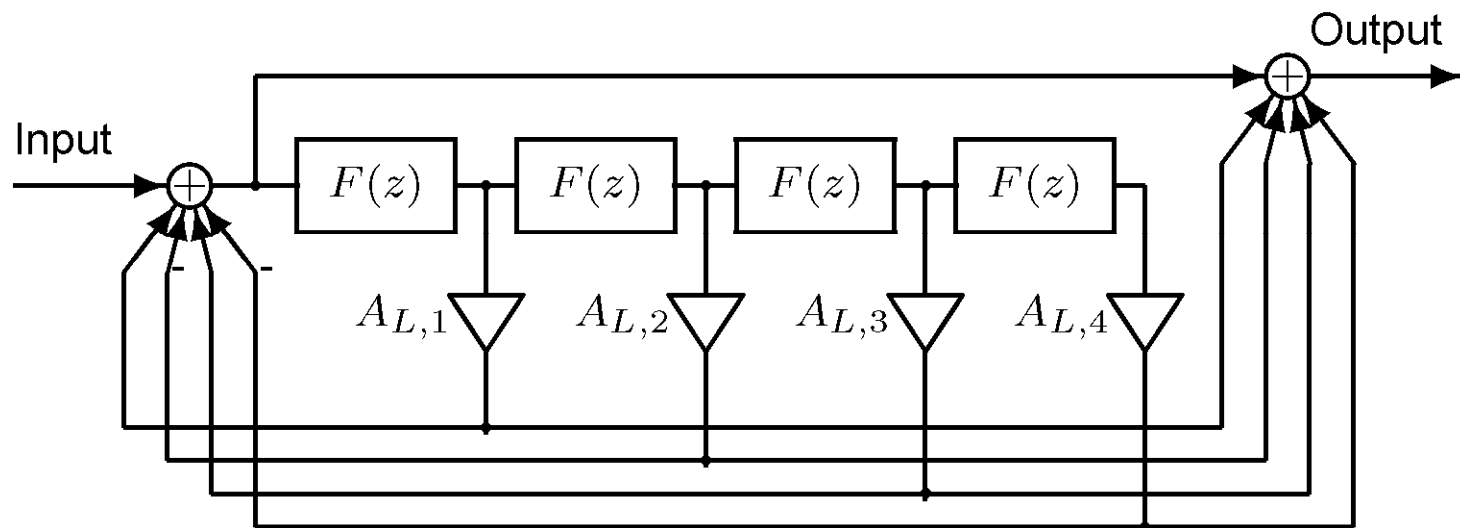
# Synthesis Filter

$$D(z) = \exp F(z), \quad F(z) = \sum_{m=0}^M c(m) \tilde{z}^{-m}$$



# MLSA Filter

$$D(z) = \exp F(z) \simeq \frac{1 + \sum_{l=1}^L A_{L,l} \{F(z)\}^l}{1 + \sum_{l=1}^L A_{L,l} \{-F(z)\}^l}$$

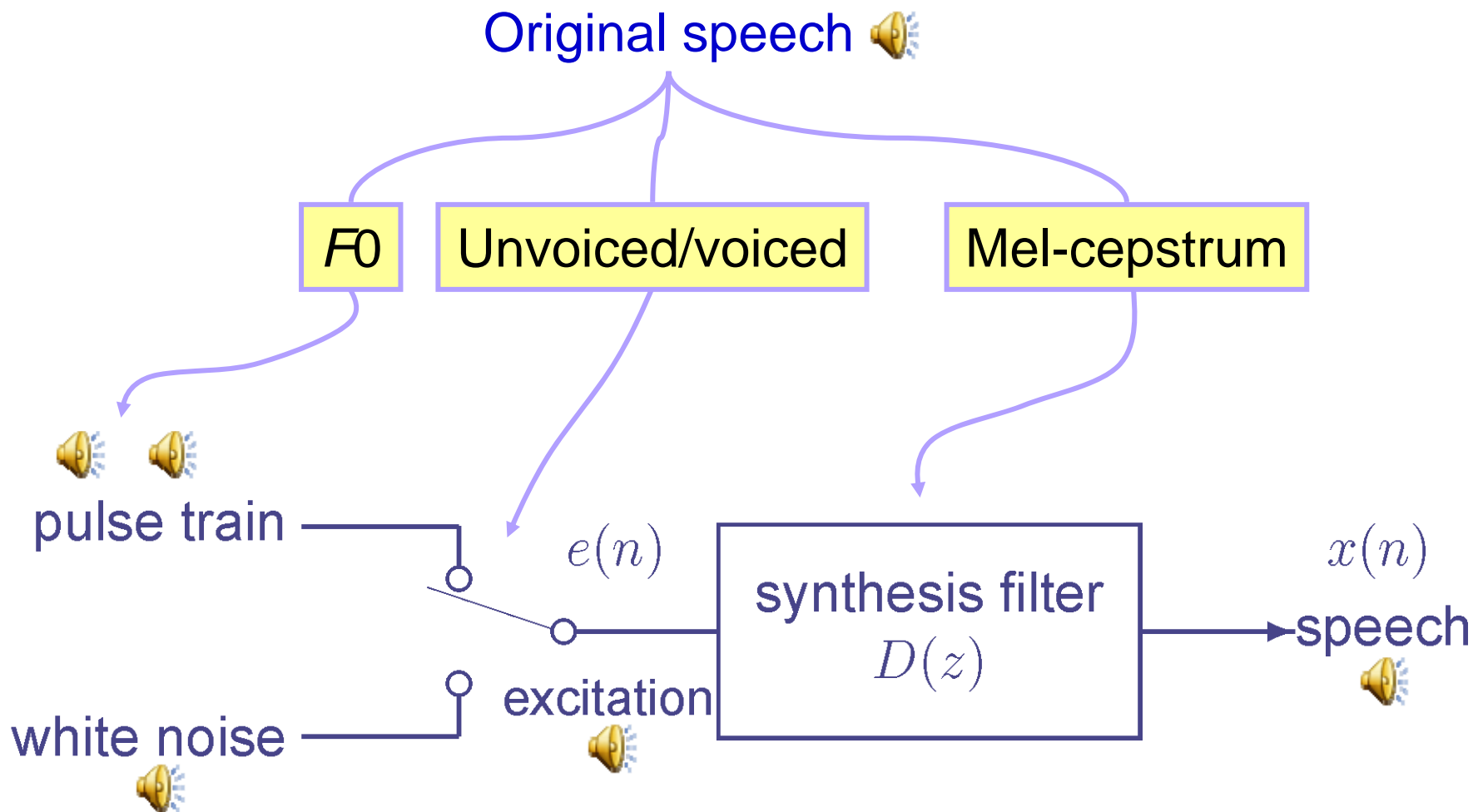


# Features of MLSA Filter

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- Filter coefficients given by mel-cepstrum
- Sufficient approximation accuracy
  - ⇒ maximum spectral error 0.24dB
- Guaranteed stability
- Computationally efficient
  - ⇒  $O(M)$  multiply-add operations a sample

# Vocoded Speech Samples

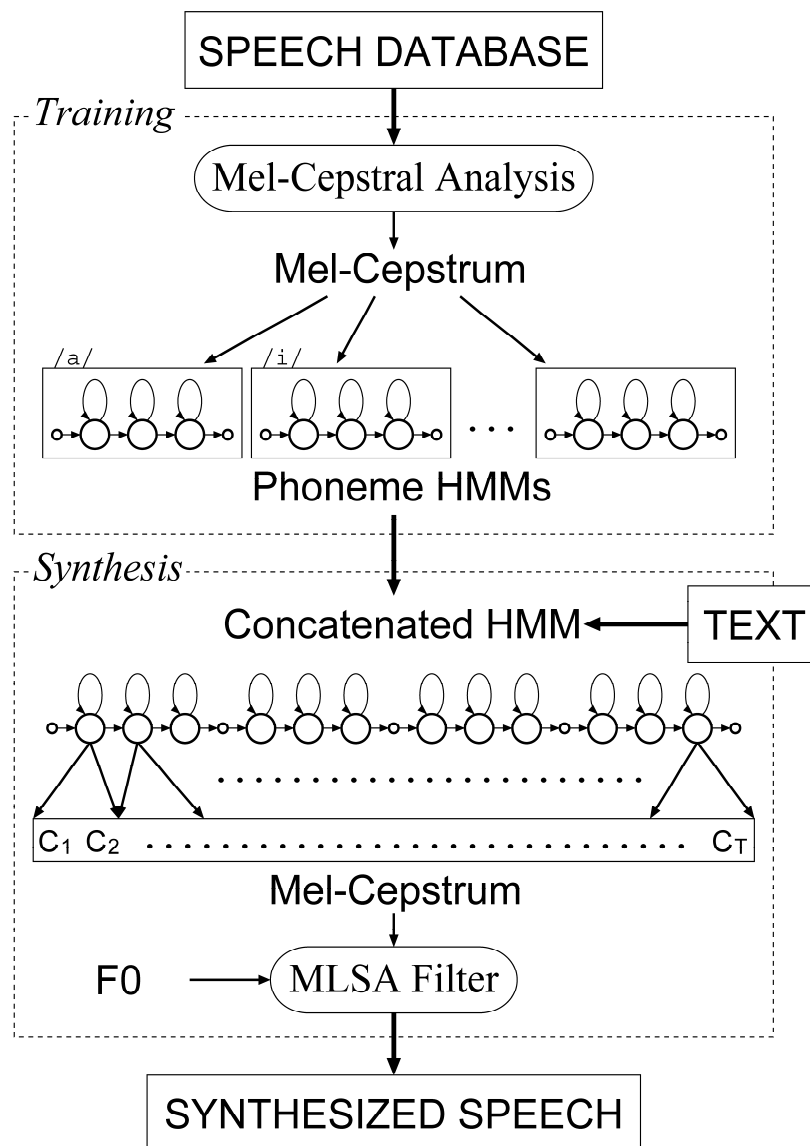


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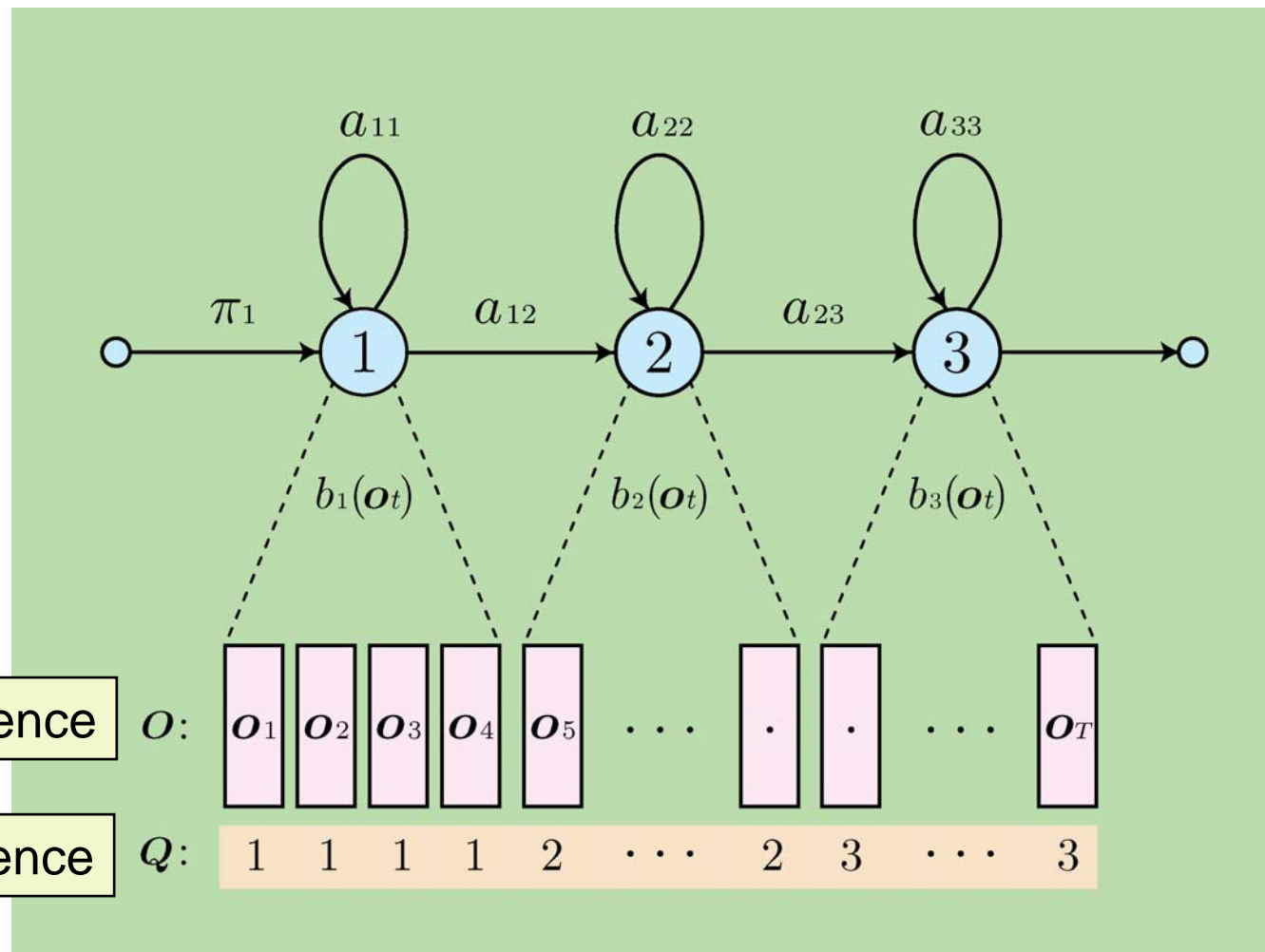
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# System Overview (only spectrum part)





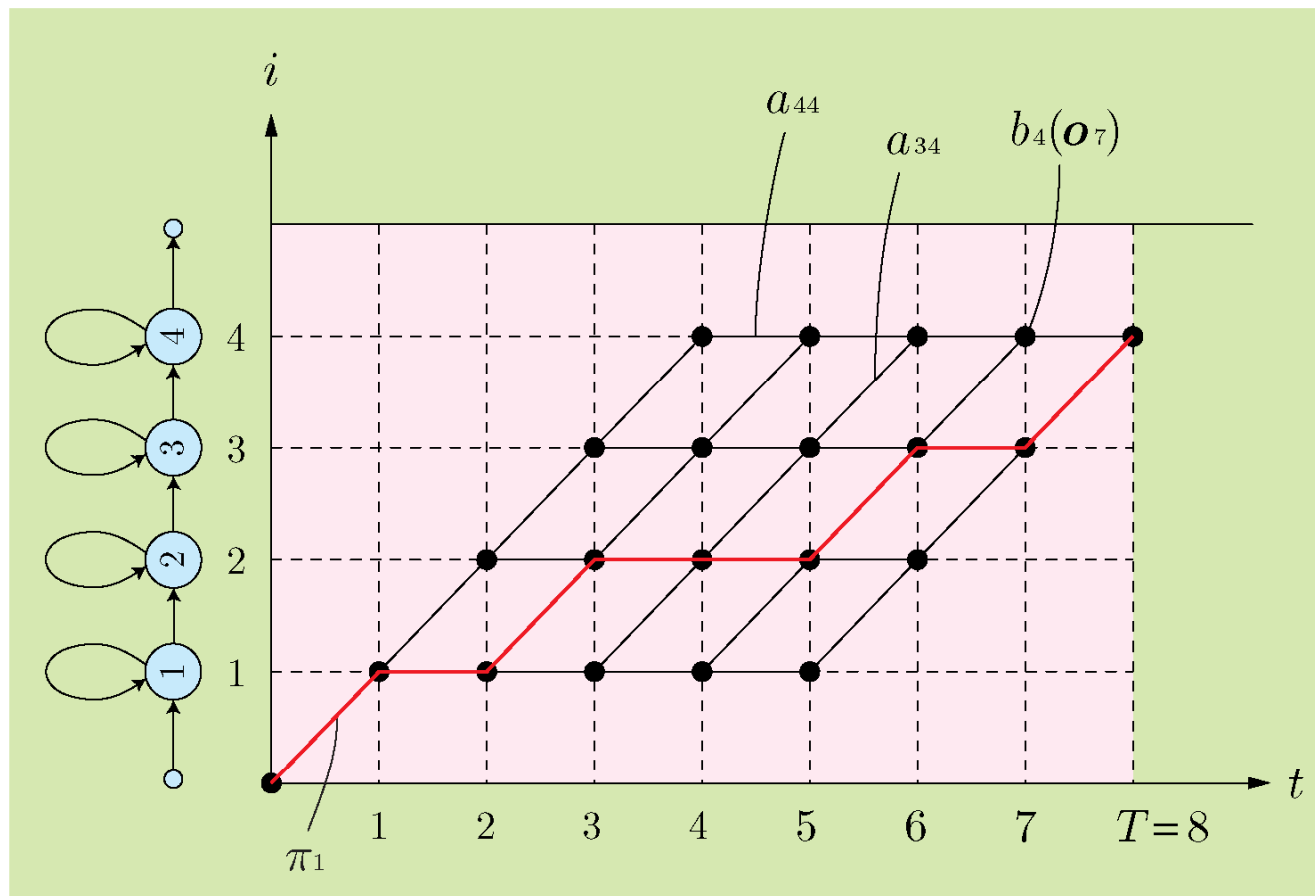
# Hidden Markov Model: HMM



State output sequence

State sequence

# Output Probability of HMM



$$P(\mathbf{O} | \lambda) = \sum_{\mathbf{Q}} P(\mathbf{O}, \mathbf{Q} | \lambda) = \sum_{\mathbf{Q}} \prod_{t=1}^T a_{q_{t-1}q_t} b_{q_t}(o_t)$$

# Speech Parameter Generation

For given HMM  $\lambda$ , determine a speech parameter vector sequence  $\mathbf{O} = [\mathbf{o}_1^\top, \mathbf{o}_2^\top, \dots, \mathbf{o}_T^\top]^\top$  which maximizes

$$\begin{aligned} P(\mathbf{O} | \lambda) &= \sum_{\mathbf{Q}} P(\mathbf{O} | \mathbf{Q}, \lambda) P(\mathbf{Q} | \lambda) \\ &\simeq \max_{\mathbf{Q}} P(\mathbf{O} | \mathbf{Q}, \lambda) P(\mathbf{Q} | \lambda) \end{aligned}$$



$$\mathbf{Q}_{\max} = \arg \max_{\mathbf{Q}} P(\mathbf{Q} | \lambda)$$

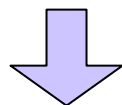
$$\mathbf{O}_{\max} = \arg \max_{\mathbf{O}} P(\mathbf{O} | \mathbf{Q}_{\max}, \lambda)$$

# Determination of State Durations

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$$P(\mathbf{Q} | \lambda) = \prod_{i=1}^K p_i(d_i)$$

Standard HMM  $\Rightarrow p_i(d_i)$  : geometric distribution



Gaussian with mean  $m_i$  and variance  $\sigma_i^2$

$$d_i = m_i, \quad i = 1, 2, \dots, K$$

# Speech Parameter Generation

For given HMM  $\lambda$ , determine a speech parameter vector sequence  $\mathbf{O} = [\mathbf{o}_1^\top, \mathbf{o}_2^\top, \dots, \mathbf{o}_T^\top]^\top$  which maximizes

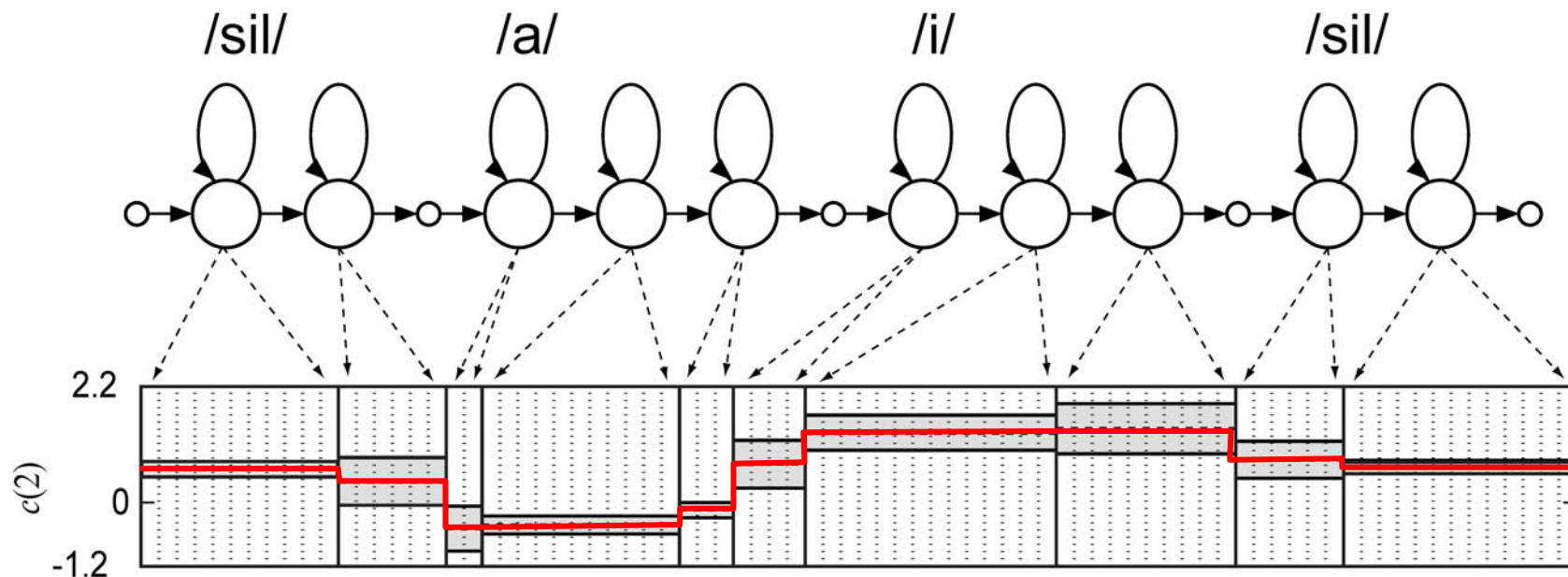
$$\begin{aligned} P(\mathbf{O} | \lambda) &= \sum_{\mathbf{Q}} P(\mathbf{O} | \mathbf{Q}, \lambda) P(\mathbf{Q} | \lambda) \\ &\simeq \max_{\mathbf{Q}} P(\mathbf{O} | \mathbf{Q}, \lambda) P(\mathbf{Q} | \lambda) \end{aligned}$$



$$\mathbf{Q}_{\max} = \arg \max_{\mathbf{Q}} P(\mathbf{Q} | \lambda)$$

$$\mathbf{O}_{\max} = \arg \max_{\mathbf{O}} P(\mathbf{O} | \mathbf{Q}_{\max}, \lambda)$$

# Without Dynamic Feature



$O$  becomes a sequence of mean vectors.

# Integration of Dynamic Feature

$$\begin{array}{c}
 \begin{array}{c}
 \mathbf{o} \\
 \begin{array}{c}
 c_t \\
 \Delta c_t \\
 \Delta^2 c_t \\
 \vdots \\
 c_t \\
 \Delta c_t \\
 \Delta^2 c_t
 \end{array}
 \end{array}
 \begin{array}{c}
 o_1 \\
 \vdots \\
 o_T
 \end{array}
 \begin{array}{c}
 3MT \\
 \vdots \\
 3MT
 \end{array}
 \end{array}
 =
 \begin{array}{c}
 \mathbf{W} \\
 \begin{array}{c}
 \begin{array}{c|c|c|c}
 1 & 0 & 0 & \cdots \\
 0 & \frac{1}{2} & 0 & \cdots \\
 2 & -1 & 0 & \cdots \\
 0 & 1 & 0 & \cdots
 \end{array} \\
 \vdots \\
 \begin{array}{c|c|c|c}
 \cdots & 0 & 0 & 1 \\
 \cdots & 0 & -\frac{1}{2} & 0 \\
 \cdots & 0 & -1 & 2
 \end{array}
 \end{array}
 \end{array}
 \begin{array}{c}
 MT \\
 \vdots \\
 MT
 \end{array}
 \begin{array}{c}
 \mathbf{c} \\
 c_1 \\
 \vdots \\
 c_T
 \end{array}
 \end{array}$$

# Solution for The Problem

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By setting

$$\frac{\partial \log P(\mathbf{W}\mathbf{C} \mid \mathbf{Q}_{max}, \lambda)}{\partial \mathbf{C}} = 0$$

we obtaine

$$\mathbf{W}^\top \mathbf{U}^{-1} \mathbf{W} \mathbf{C} = \mathbf{W}^\top \mathbf{U}^{-1} \mathbf{M}$$

where

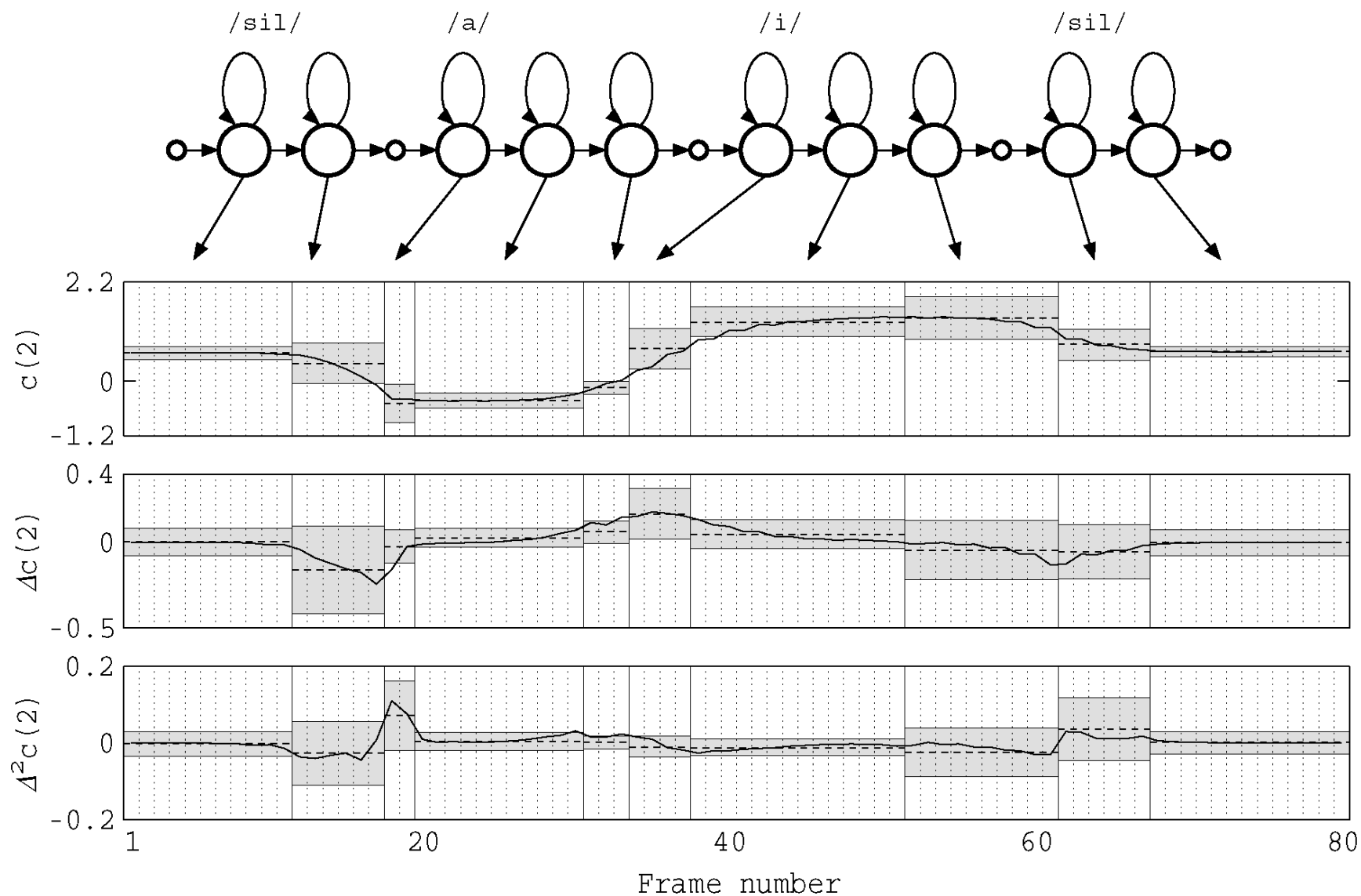
$$\mathbf{C} = \left[ \mathbf{c}_1^\top, \mathbf{c}_2^\top, \dots, \mathbf{c}_T^\top \right]^\top$$

$$\mathbf{M} = \left[ \boldsymbol{\mu}_{q_1}^\top, \boldsymbol{\mu}_{q_2}^\top, \dots, \boldsymbol{\mu}_{q_T}^\top \right]^\top$$

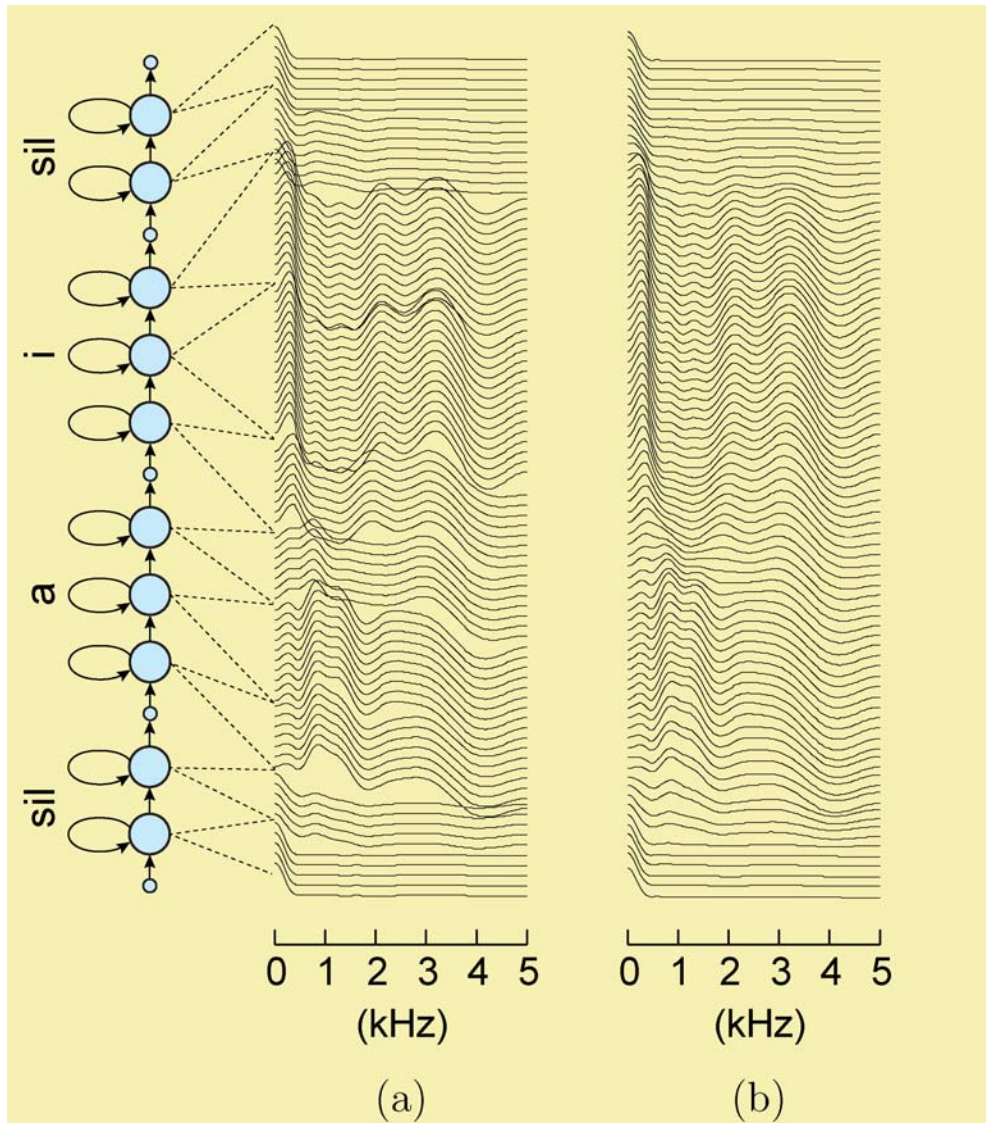
$$\mathbf{U}^{-1} = \text{diag} \left[ \mathbf{U}_{q_1}^{-1}, \mathbf{U}_{q_2}^{-1}, \dots, \mathbf{U}_{q_T}^{-1} \right]$$



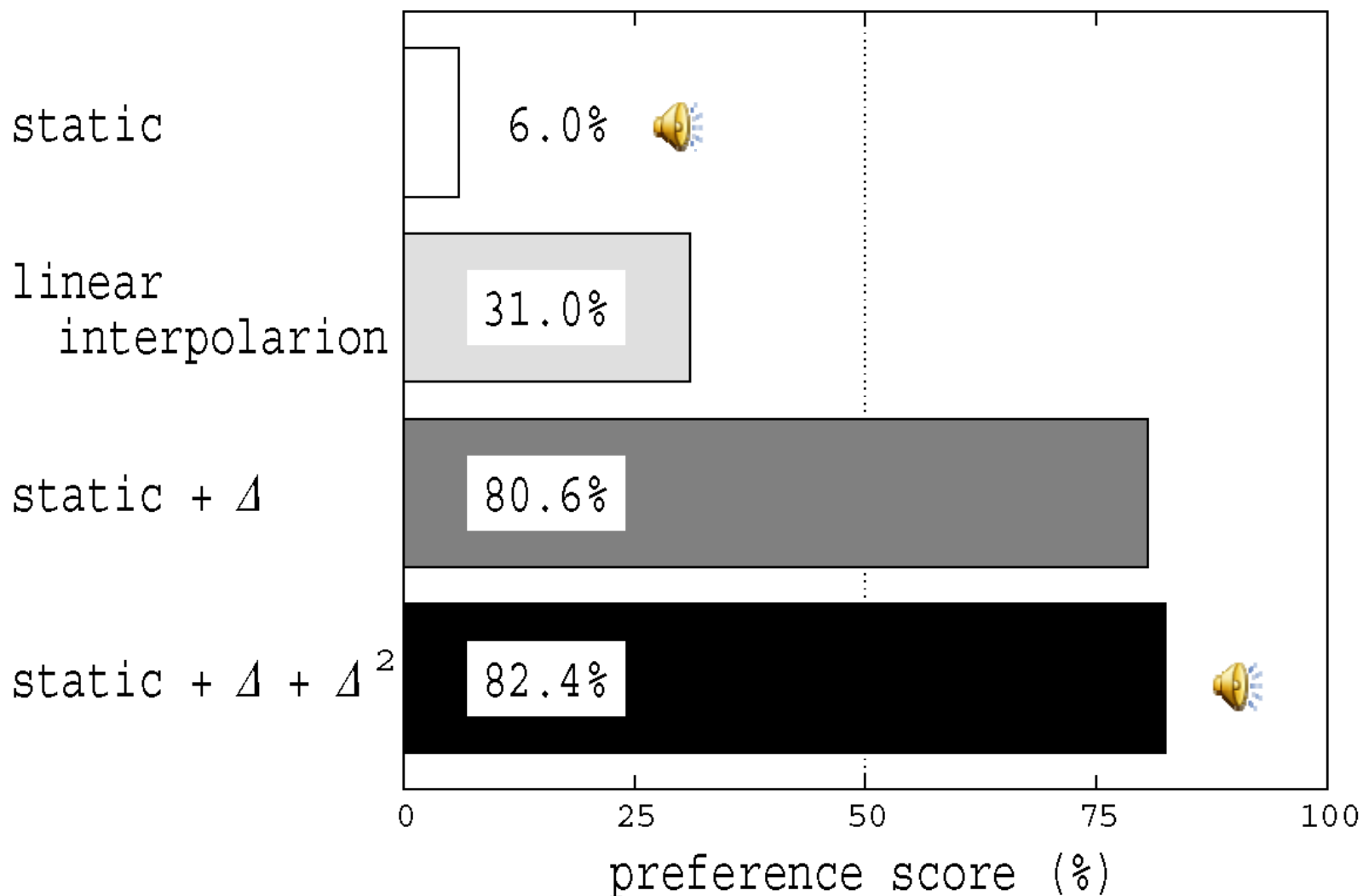
# Generated Speech Parameter



# Generated Spectra



# Effect of Dynamic Features

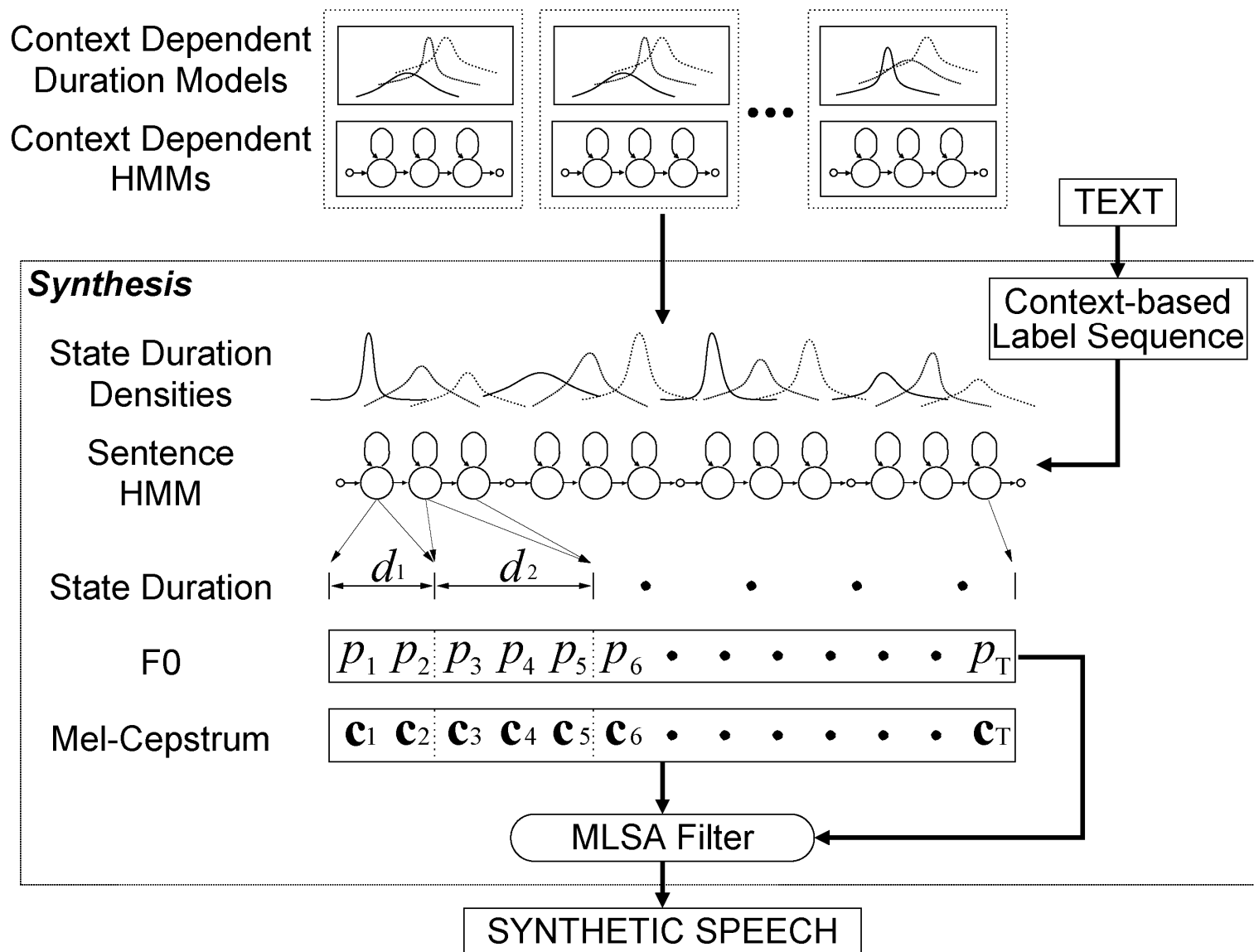


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# HMM-Based Speech Synthesis System



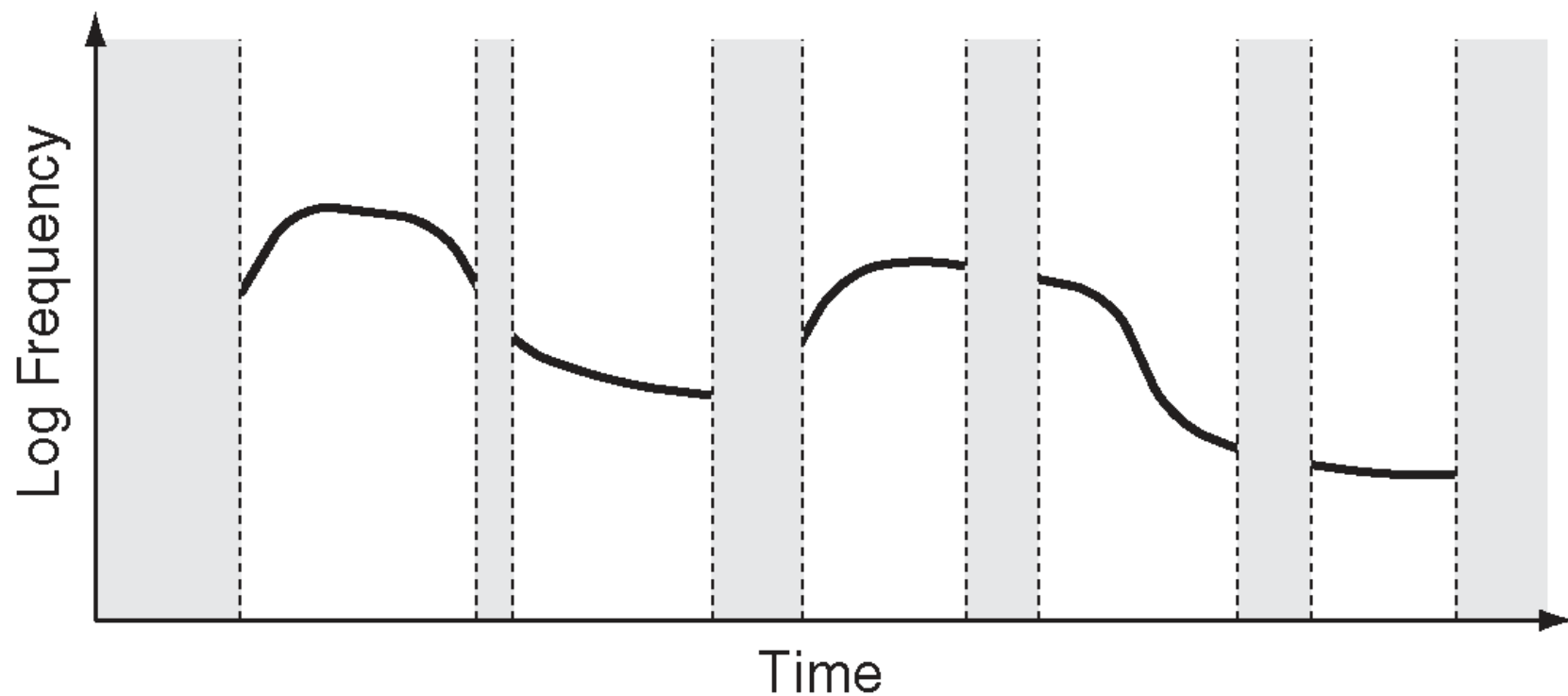
# Observation of $F_0$

Voiced

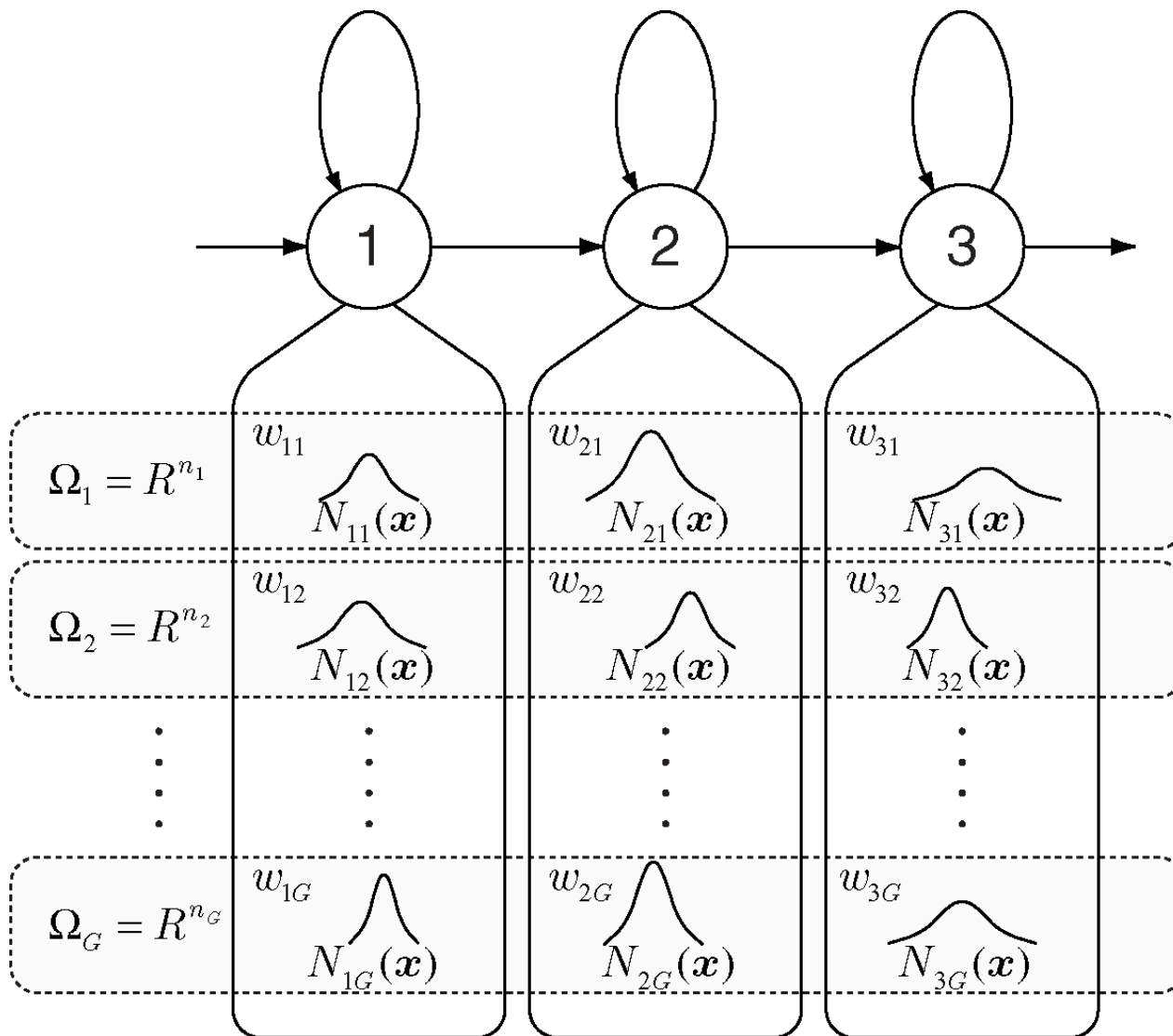
$$\Omega_1 = R^1 \frac{\text{bell curve}}{N_1(x)}$$

Unvoiced

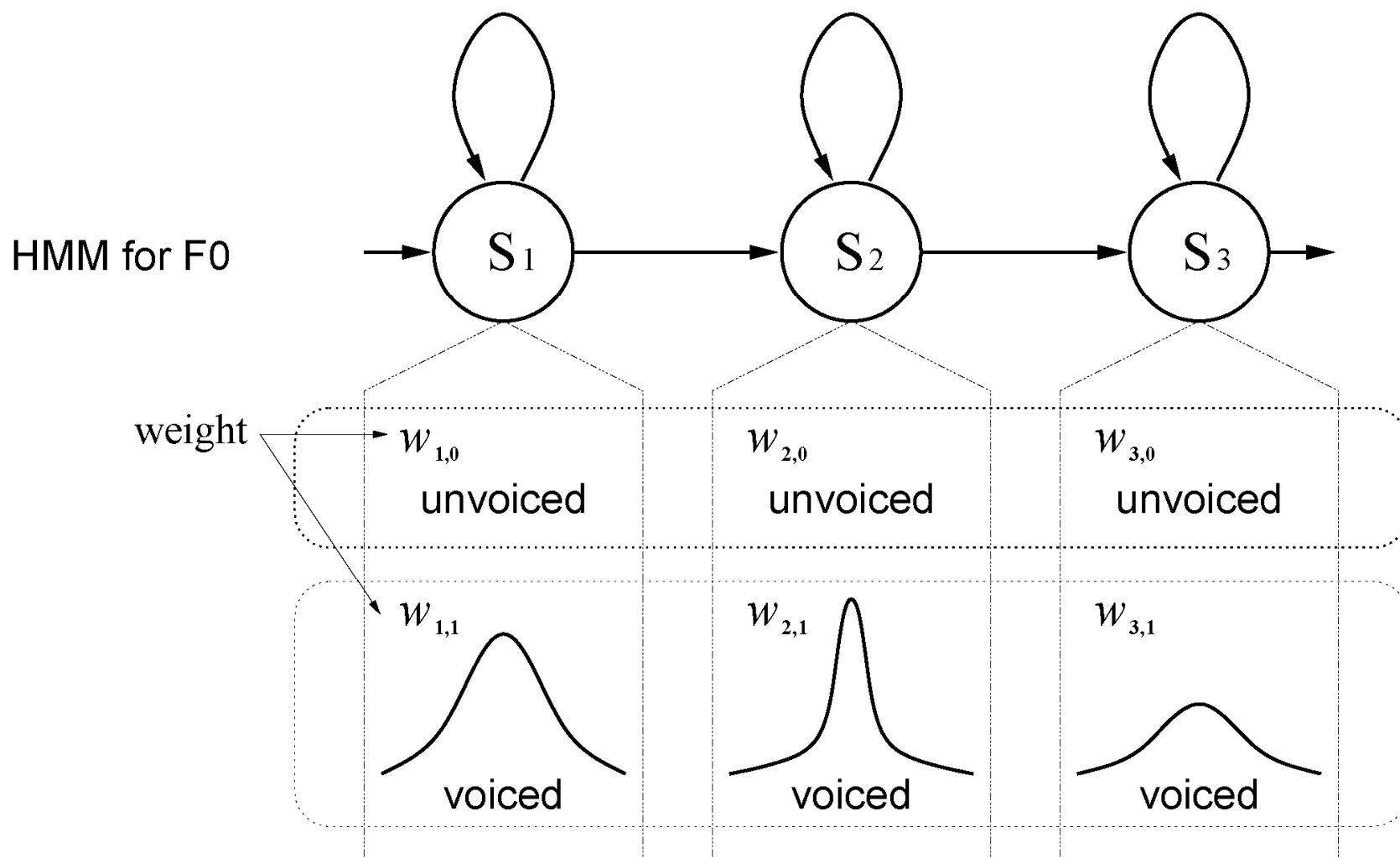
$$\Omega_2 = R^0$$



# MSD-HMM

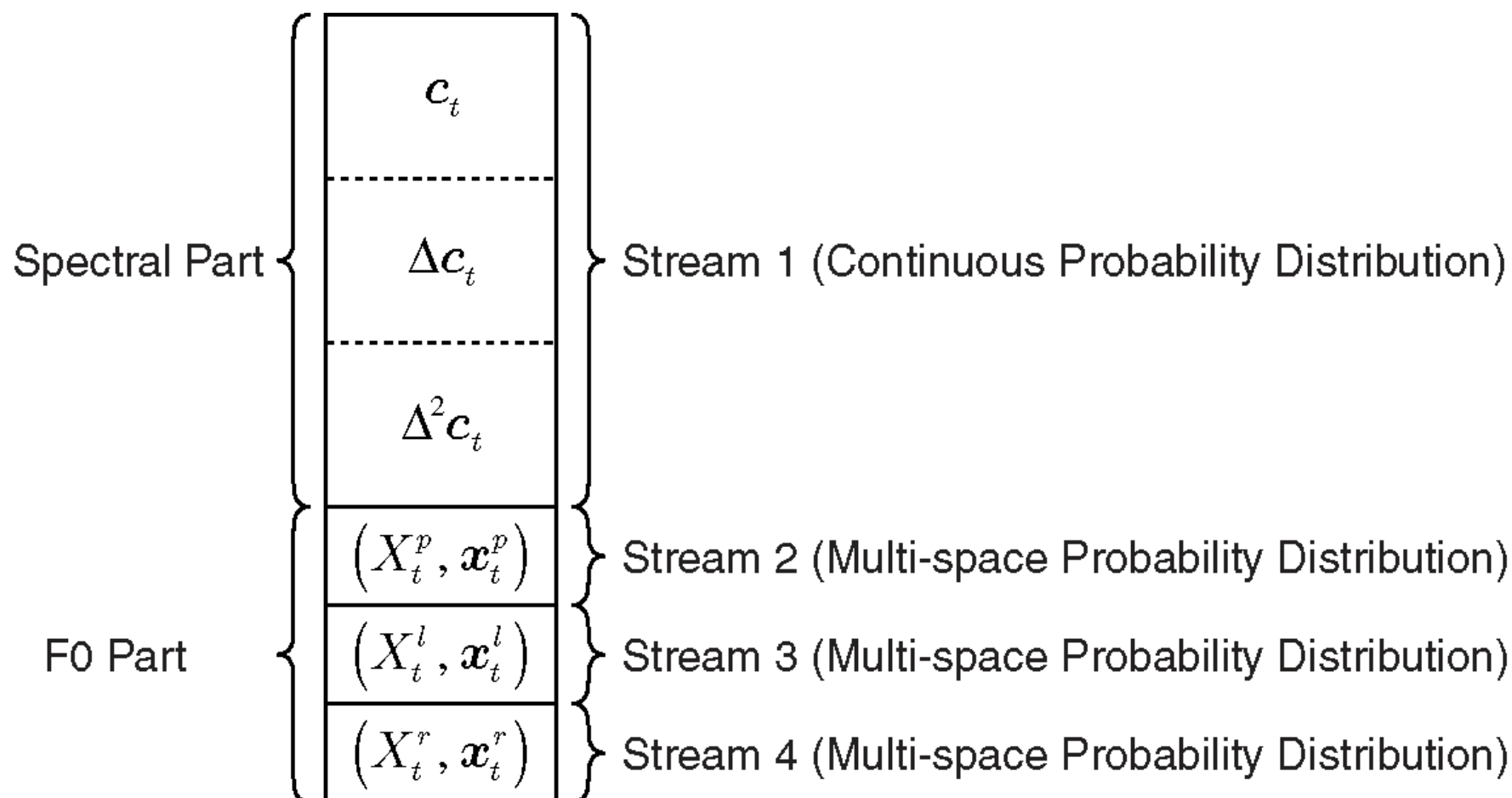


# MSD-HMM for $F_0$ Modeling

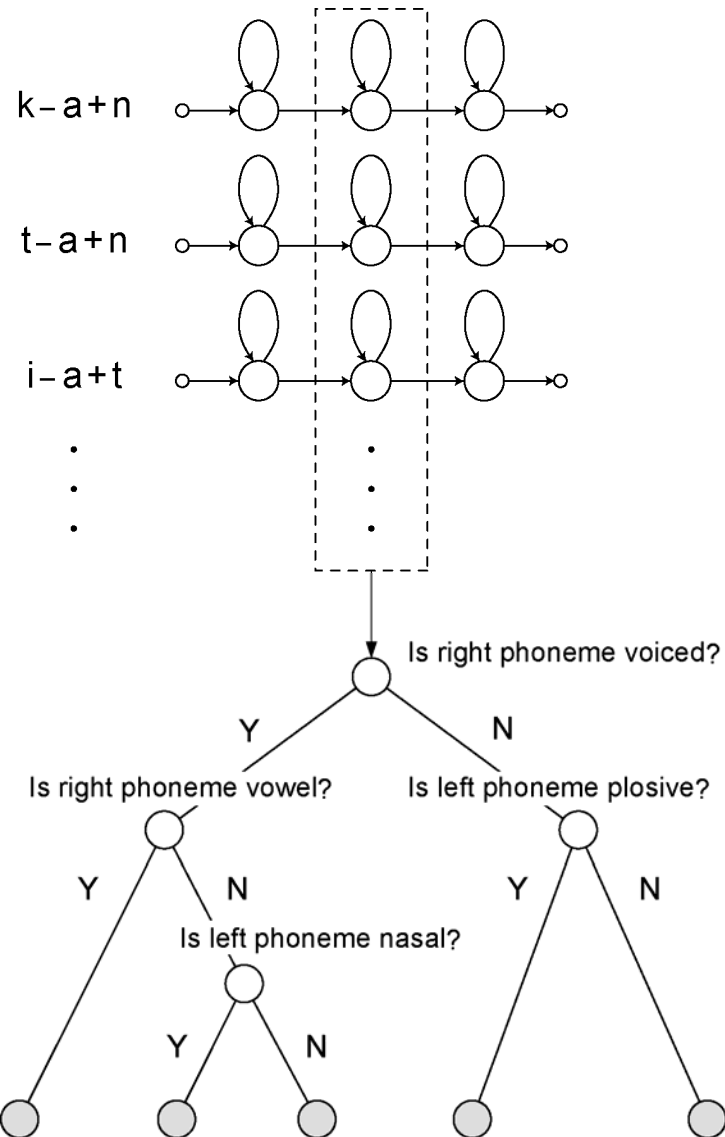




# State Output Vector



# Context Clustering



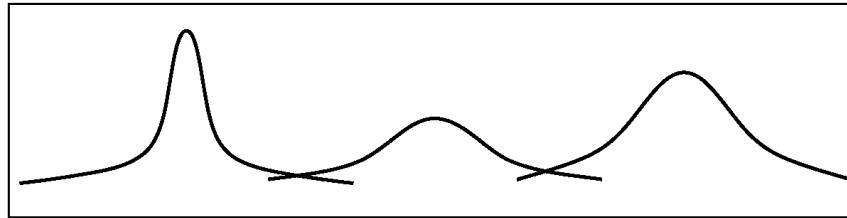
# Context Clustering: Factors

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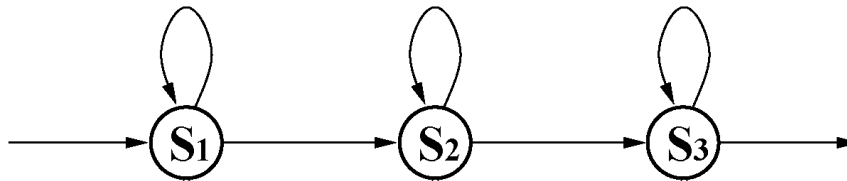
- ❑ {preceding, current, succeeding} phoneme
- ❑ Position of current phoneme in current syllable
- ❑ Number of phonemes at {preceding, current, succeeding} syllable
- ❑ Accent of {preceding, current, succeeding} syllable
- ❑ Position of current syllable in current word
- ❑ Number of {preceding, succeeding} stressed syllables in current phrase
- ❑ Number of {preceding, succeeding} accented syllables in current phrase
- ❑ Number of syllables {from previous, to next} stressed syllable
- ❑ Number of syllables {from previous, to next} accented syllable
- ❑ Vowel within current syllable
- ❑ Guess at part of speech of {preceding, current, succeeding} word
- ❑ Number of syllables in {preceding, current, succeeding} word
- ❑ Position of current word in current phrase
- ❑ Number of {preceding, succeeding} content words in current phrase
- ❑ Number of words {from previous, to next} content word
- ❑ Number of syllables in {preceding, current, succeeding} phrase
- ❑ Position in major phrase
- ❑ ToBI endtone of current phrase

# Context Clustering: HMM Structure

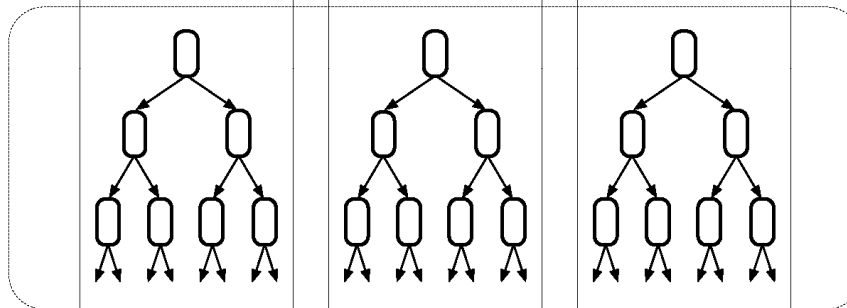
State Duration Model



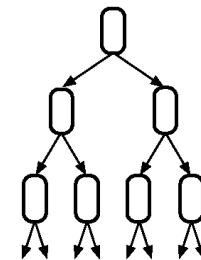
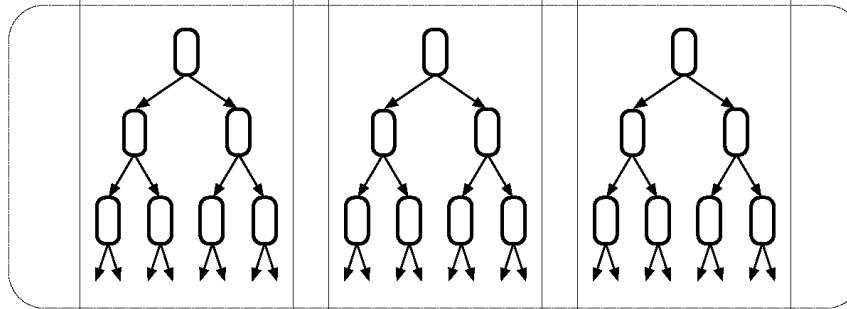
HMM  
for Spectrum  
and F0



Decision Tree  
for  
Spectrum

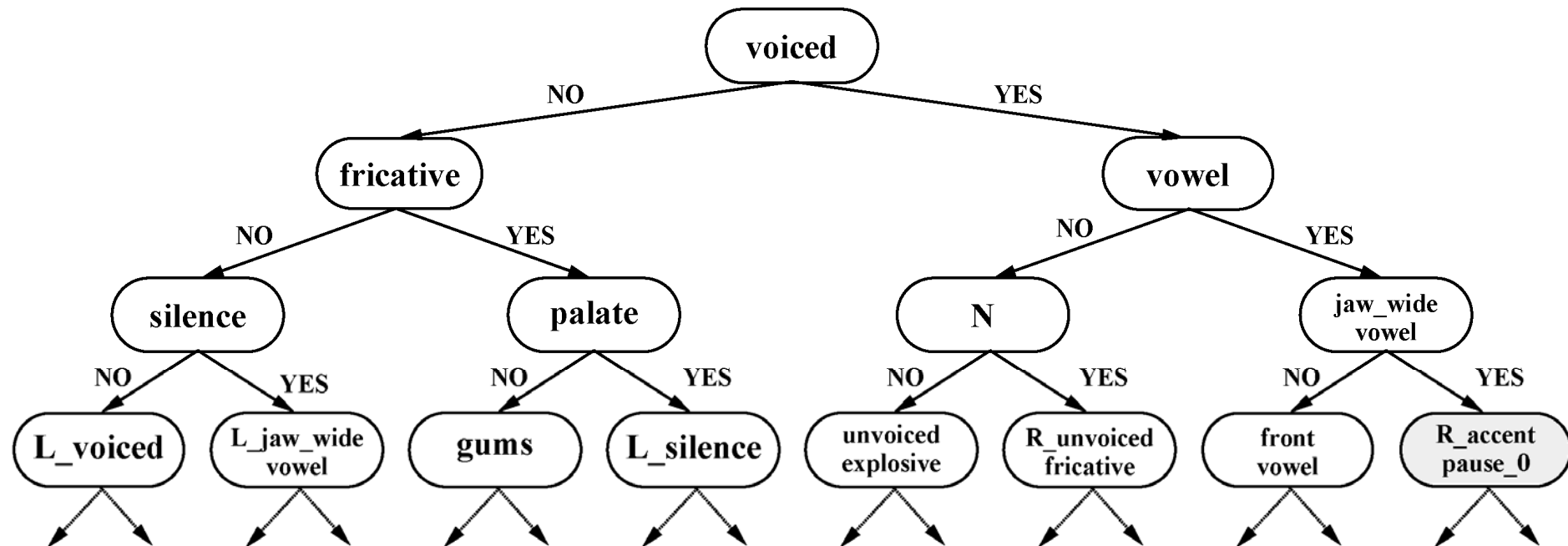


Decision Tree  
for  
F0



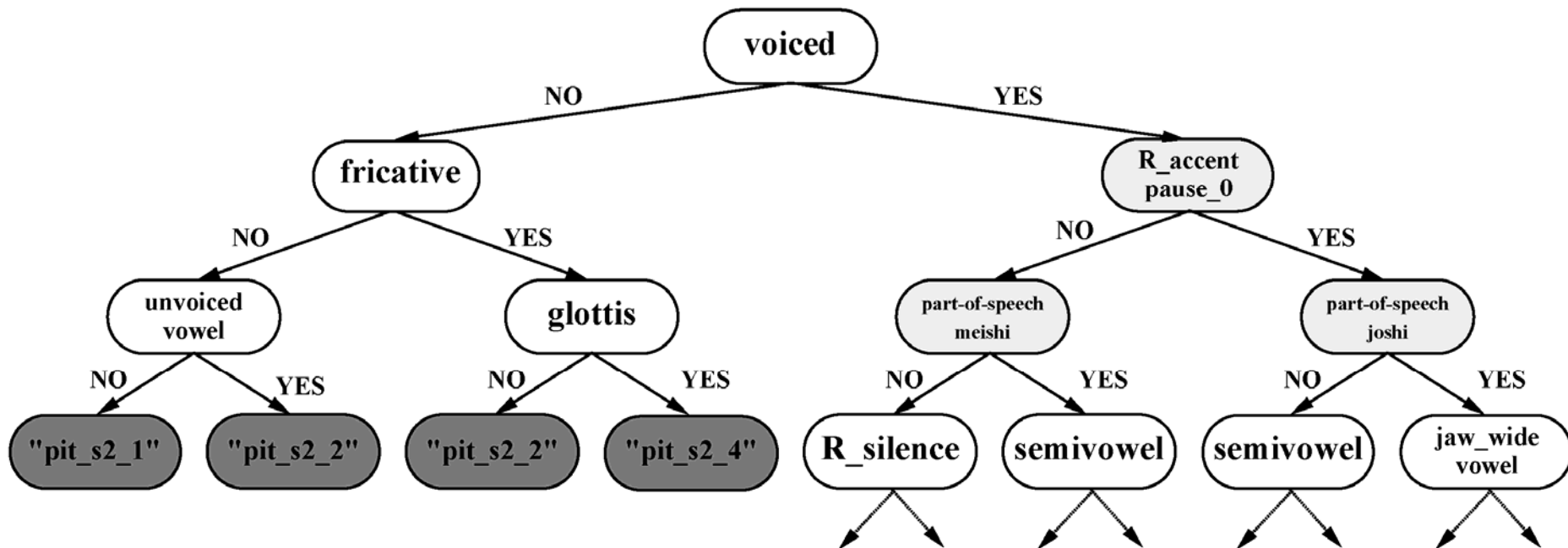
Decision Tree  
for  
State Duration Model

# Tree for Spectrum (1<sup>st</sup> state)



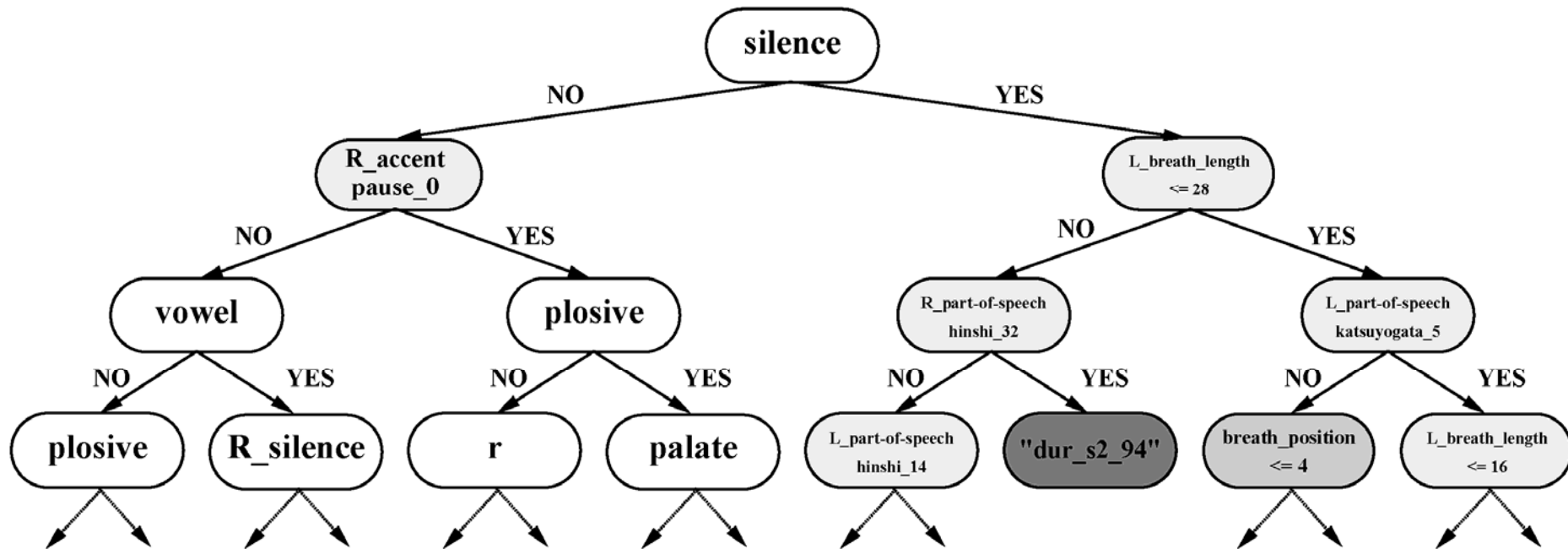
□ Questions about phonetic attributes

# Tree for F0 (1<sup>st</sup> state)



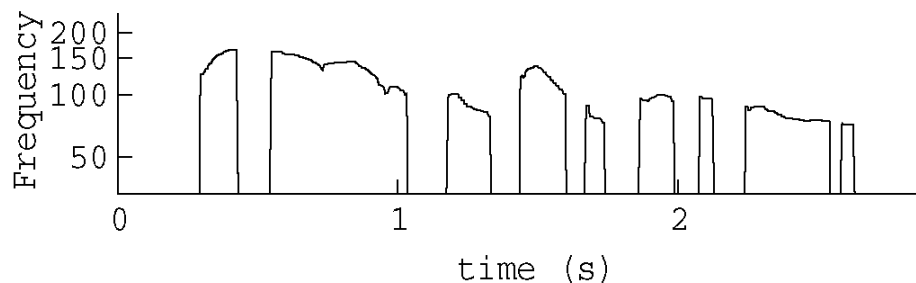
□ Questions about linguistic attributes

# Tree for State Duration

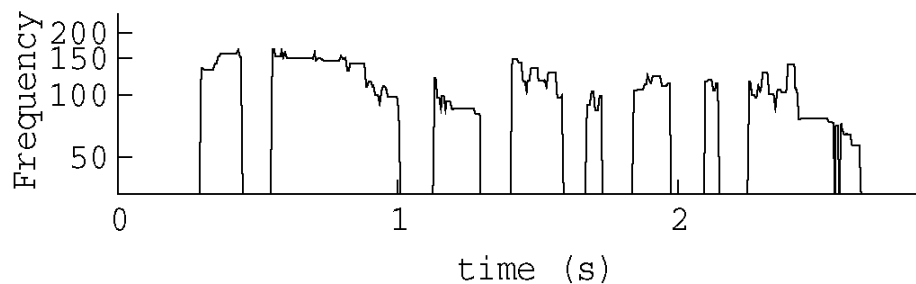


- Linguistic questions for pause
- Phonetic questions for speech

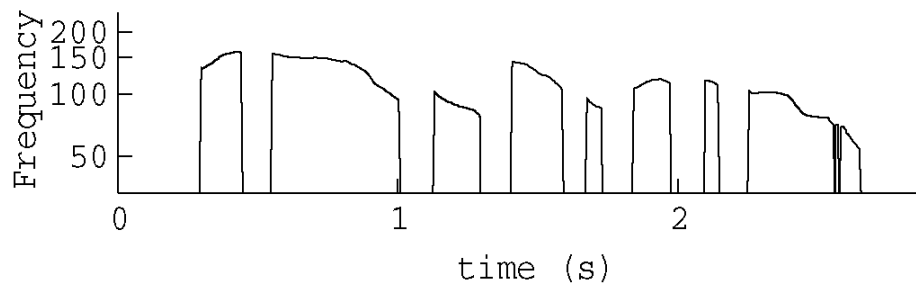
# Generated *F0*



natural speech



without dynamic features



with dynamic features ( $\Delta + \Delta^2$ )



# Effect of Dynamic Feature

**Subjective Evaluation Result  
(Preference Score)**

		Dynamic feature of spectrum	
		with	without
Dynamic feature of $F_0$	with	91.3% 📢	37.5% 📢
	without	35.8% 📢	11.8% 📢

「小さな鰻屋に、熱気のようなものがみなぎる」  
“Chiisana unagiya ni, nekkino youna monoga minagiru”

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# Recent Improvements

- Introduction of “hidden semi-Markov models”
- STRAIGHT vocoding
- Parameter generation considering global variance (GV)

⇒ Now, it is competitive to state-of-the-art unit selection systems

■ Basic system



■ 2005



■ 2006



One-hour  
training data

Five-hour  
training data

# Evaluation: Blizzard Challenge

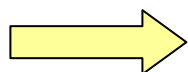
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## □ Speech Recognition

Comparison on common datasets has been improving the core technology, e.g., DARPA, NIST

## □ Speech Synthesis

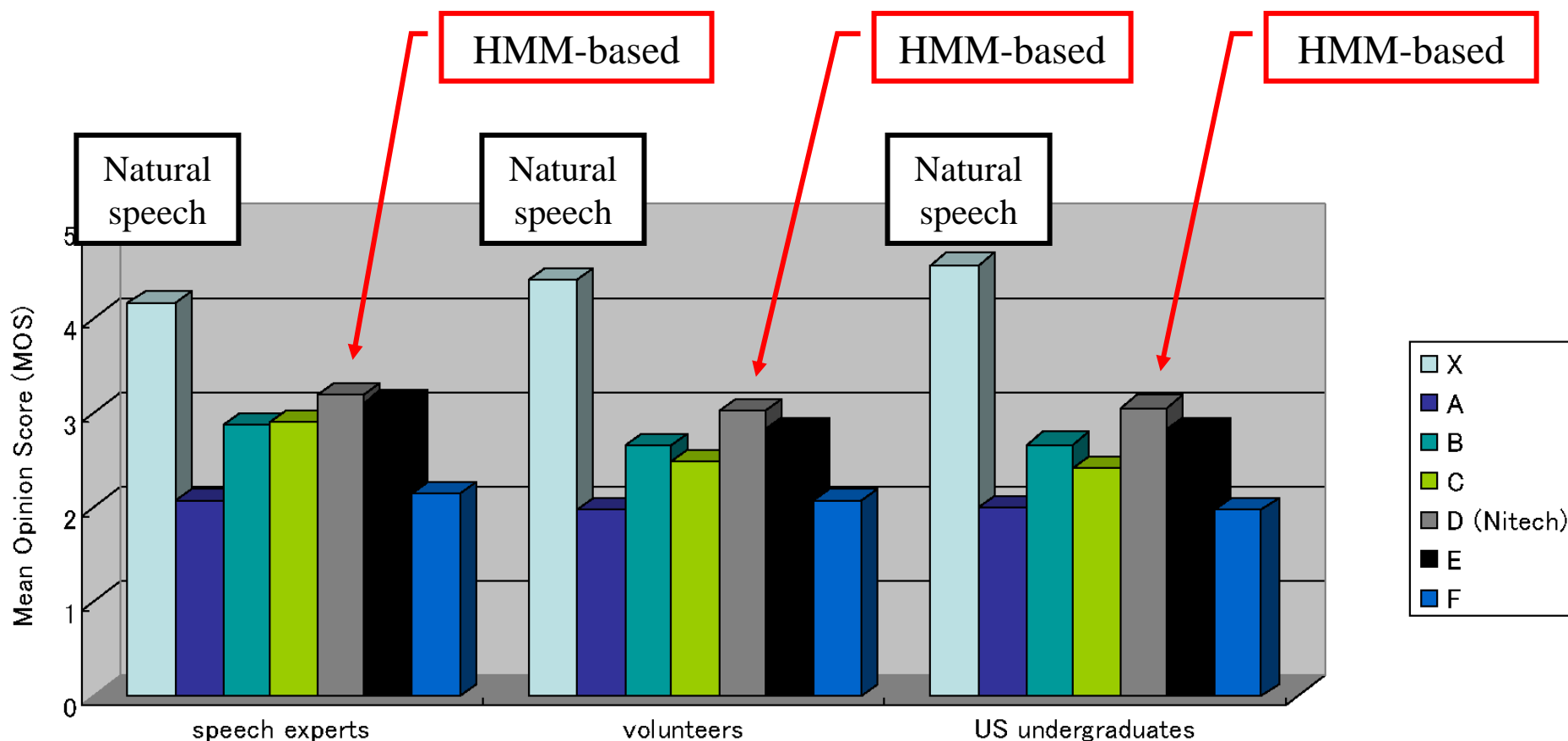
It is necessary to compare speech synthesis techniques on common datasets



Blizzard Challenge 2005 and 2006

# Results of Blizzard Challenge 2005

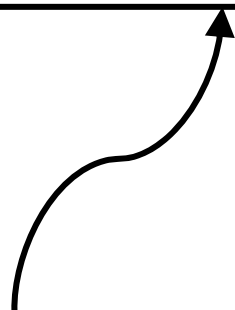
ARCTIC set (one hour training data)



# The Software

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**Modified HTK (HTS) + SPTK**



## Modifications to HTK:

- Stream-dependent context clustering
- State output probability for *F0* modeling
- State duration modeling and clustering

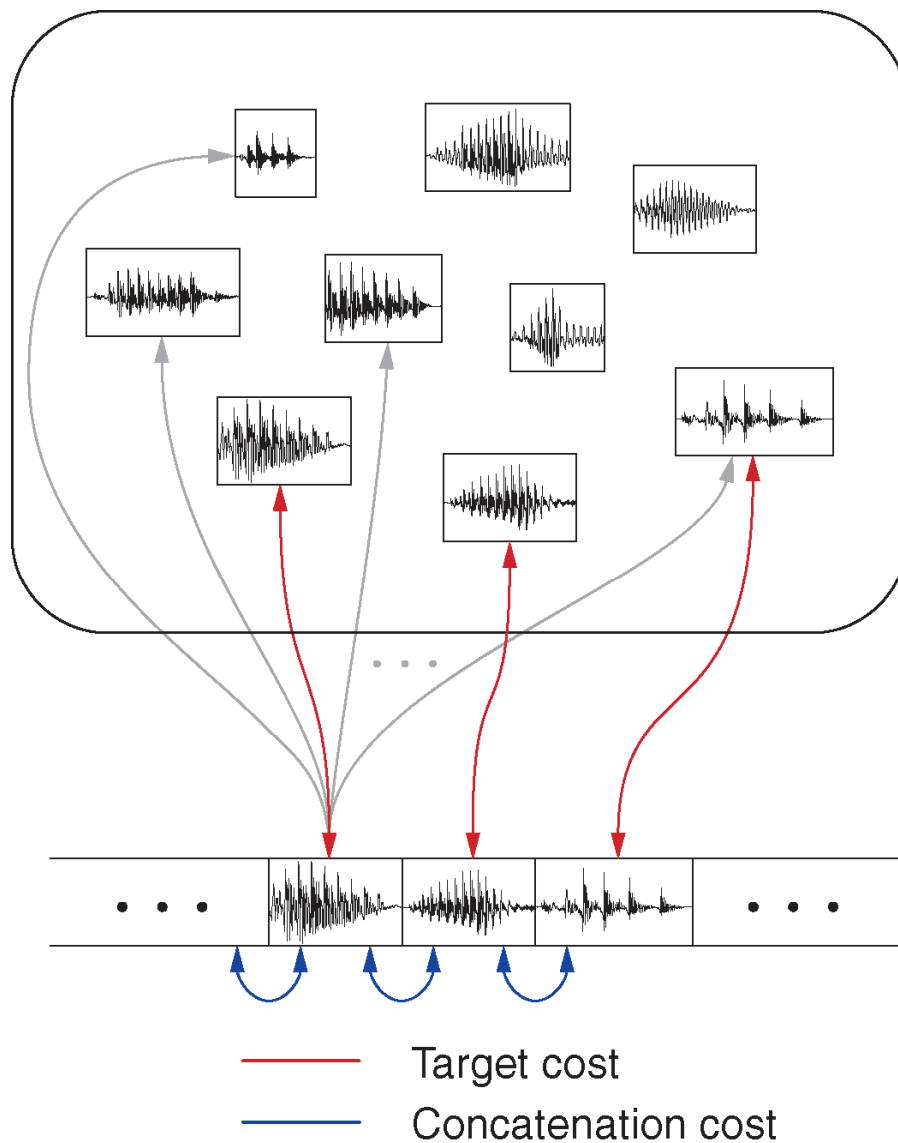
HMM-based Speech Synthesis System (HTS) (<http://hts.ics.nitech.ac.jp>)

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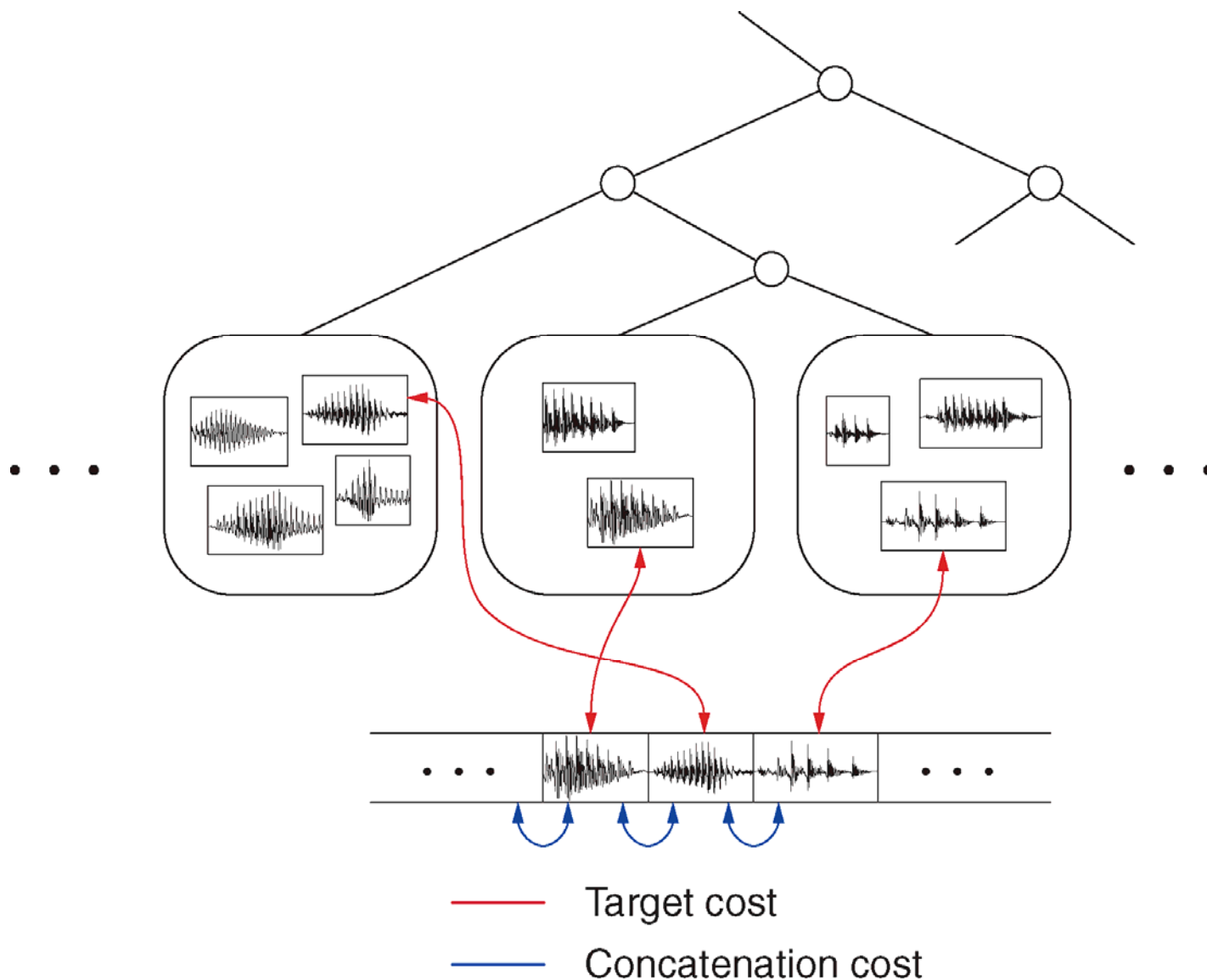
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# Unit selection





# Unit Selection Based on Clustering



# Comparison between Two Approaches

Unit selection	HMM-based
Clustering (possible use of HMM)	Clustering (use of HMM)
Multi-template of waveform	Statistics $\Rightarrow$ small footprint
Single tree for waveform (possible use of additional trees for prosody prediction)	Multiple tree for Spectrum, F0 duration
Advantage: <ul style="list-style-type: none"><li>• Waveform concatenation <math>\Rightarrow</math> high quality speech</li></ul> Disadvantage: <ul style="list-style-type: none"><li>• Discontinuity</li><li>• Hit or miss</li></ul>	Disadvantage: <ul style="list-style-type: none"><li>• Vocoder-based <math>\Rightarrow</math> buzzy</li></ul> Advantage: <ul style="list-style-type: none"><li>• Smooth</li><li>• Stable</li></ul>
• Fixed voice	• Various voices

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## □ Recent improvements and evaluation

## □ Relation to the unit selection approach

## □ Flexibility of the approach





- Speaker adaptation (mimicking voices)
- Speaker Interpolation (mixing voices)
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# What We Can Do?

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- Emotional speech synthesis
- Speaker adaptation (mimicking voices)
- Speaker interpolation (mixing voices)
- Eigenvoices (producing voices)
- Multilingual speech synthesis
- Singing voice synthesis
- Audio-visual speech synthesis
- Human motion synthesis

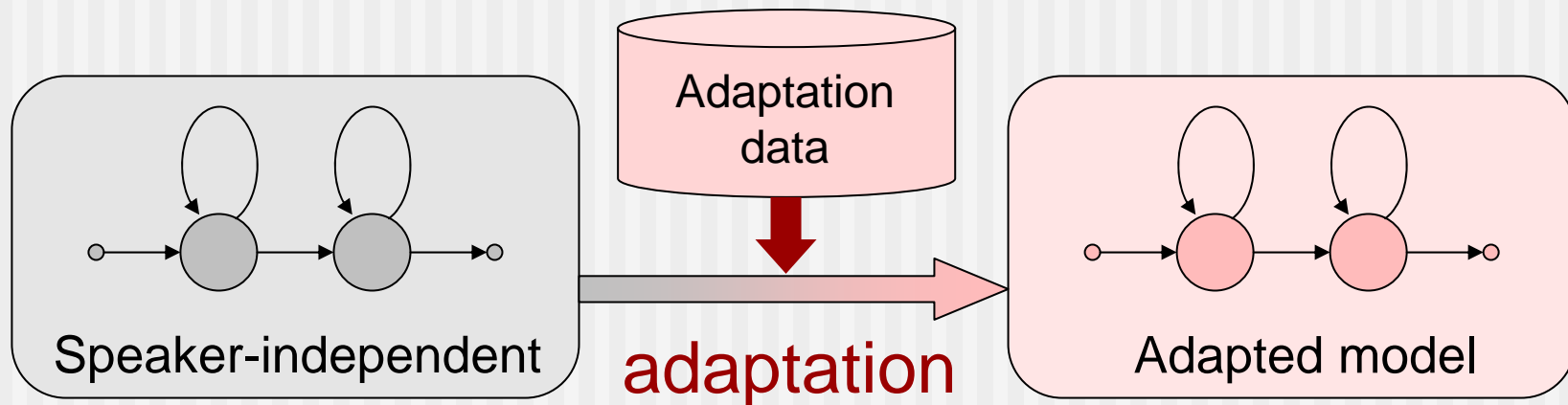
# Emotional Speech Synthesis

text	neutral	angry
「授業中に携帯いじってんじゃねえよ！ 電源切っとけ！」 “Don’t touch your cell phone during a class! Turn off it!”		
「ミーティングには毎週参加しなさい！」 “You must attend the weekly meeting!”		

trained with 200 utterances

# Speaker Adaptation (mimicking voices)

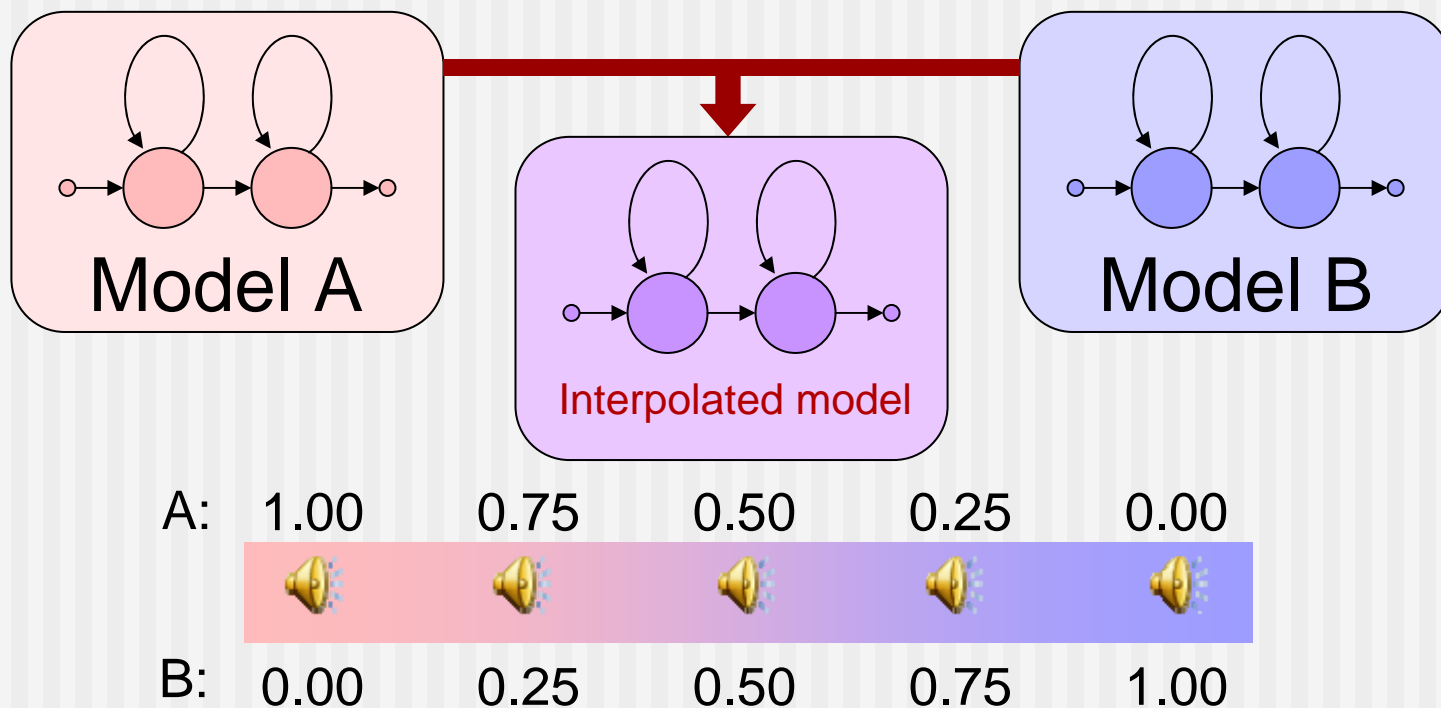
## MLLR-based adaptation



- w/o adaptation (initial model) 📢
- Adapted with 4 utterances 📢
- Adapted with 50 utterances 📢
- Speaker-dependent model 📢

# Speaker Interpolation (mixing voices)


Linear combination of two speaker-dependent models



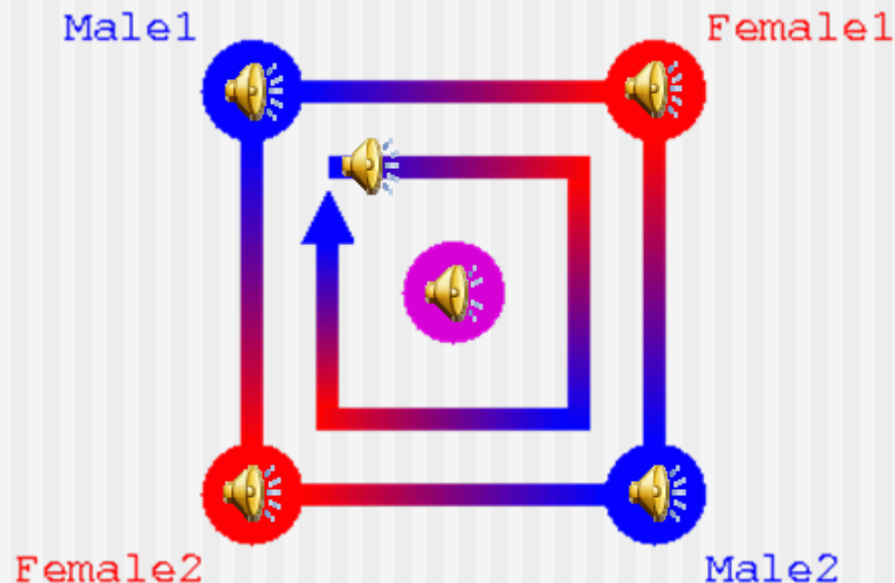
# Voice Morphing

Two voices:

 A → → → → → → → → → B

A ← ← ← ← ← ← ← ← ← B 

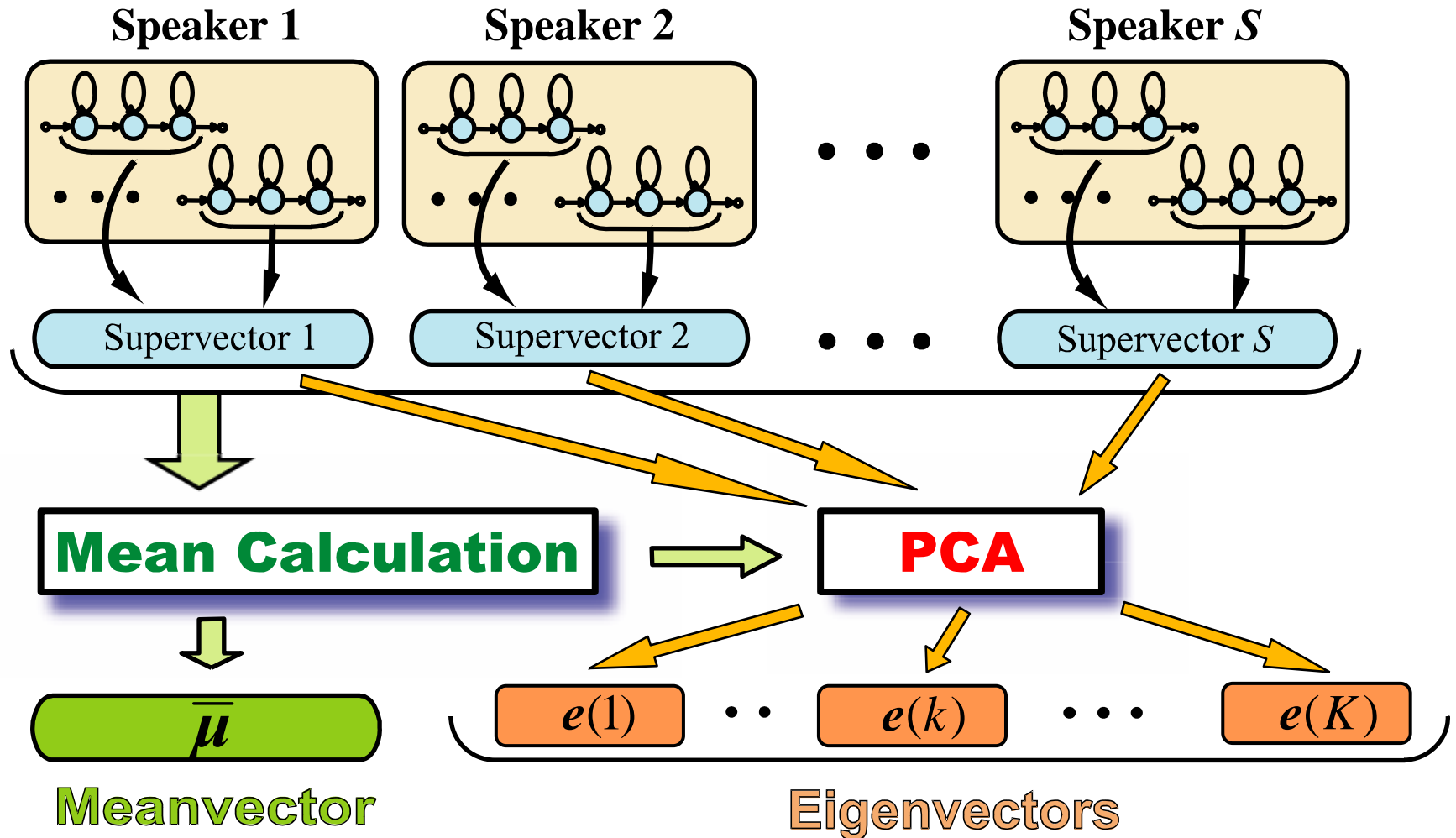
Four voices:





# Eigenvoices (producing voices)

## Speaker dependent HMM sets

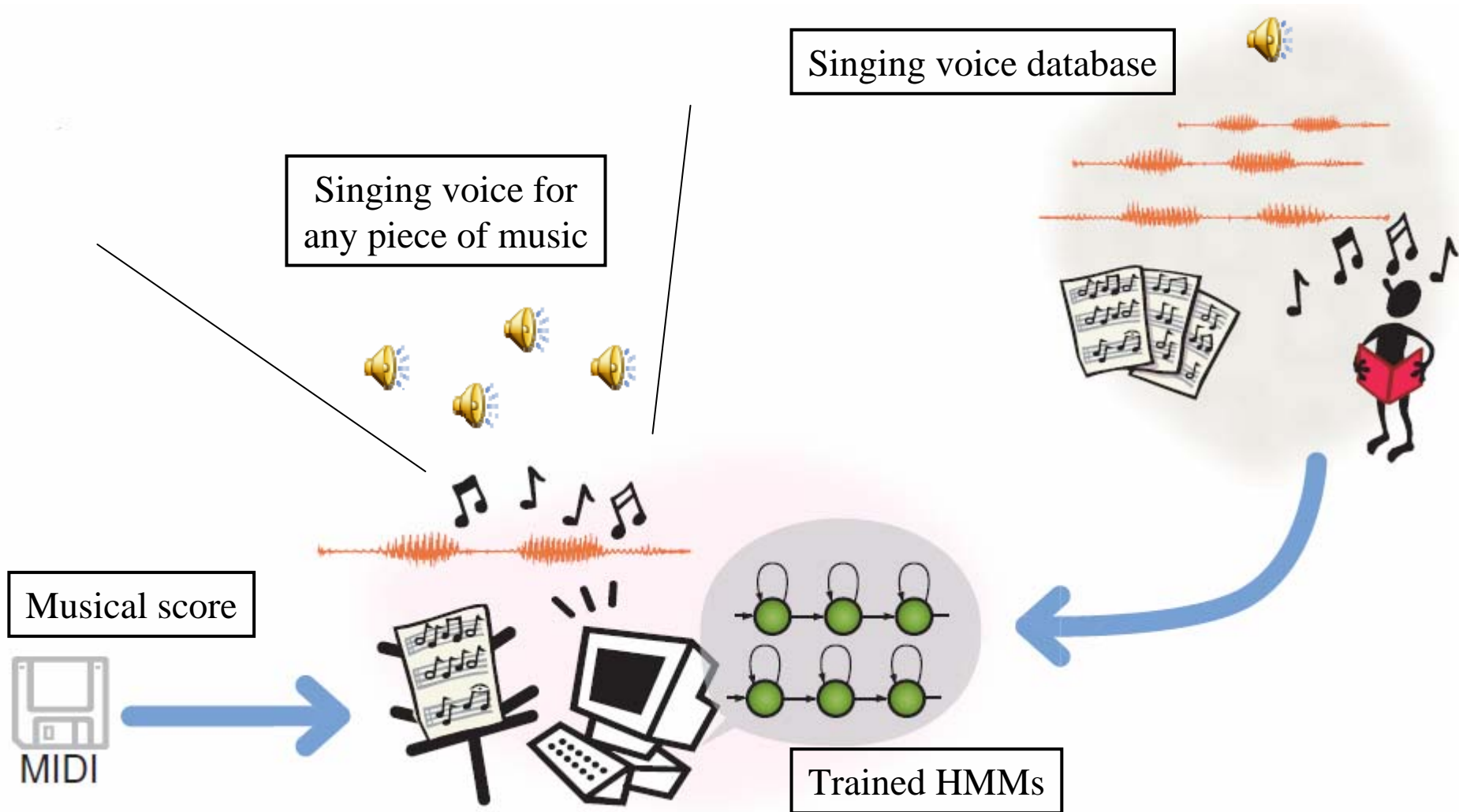


# Multilingual Speech Synthesis

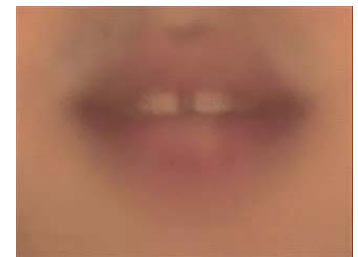
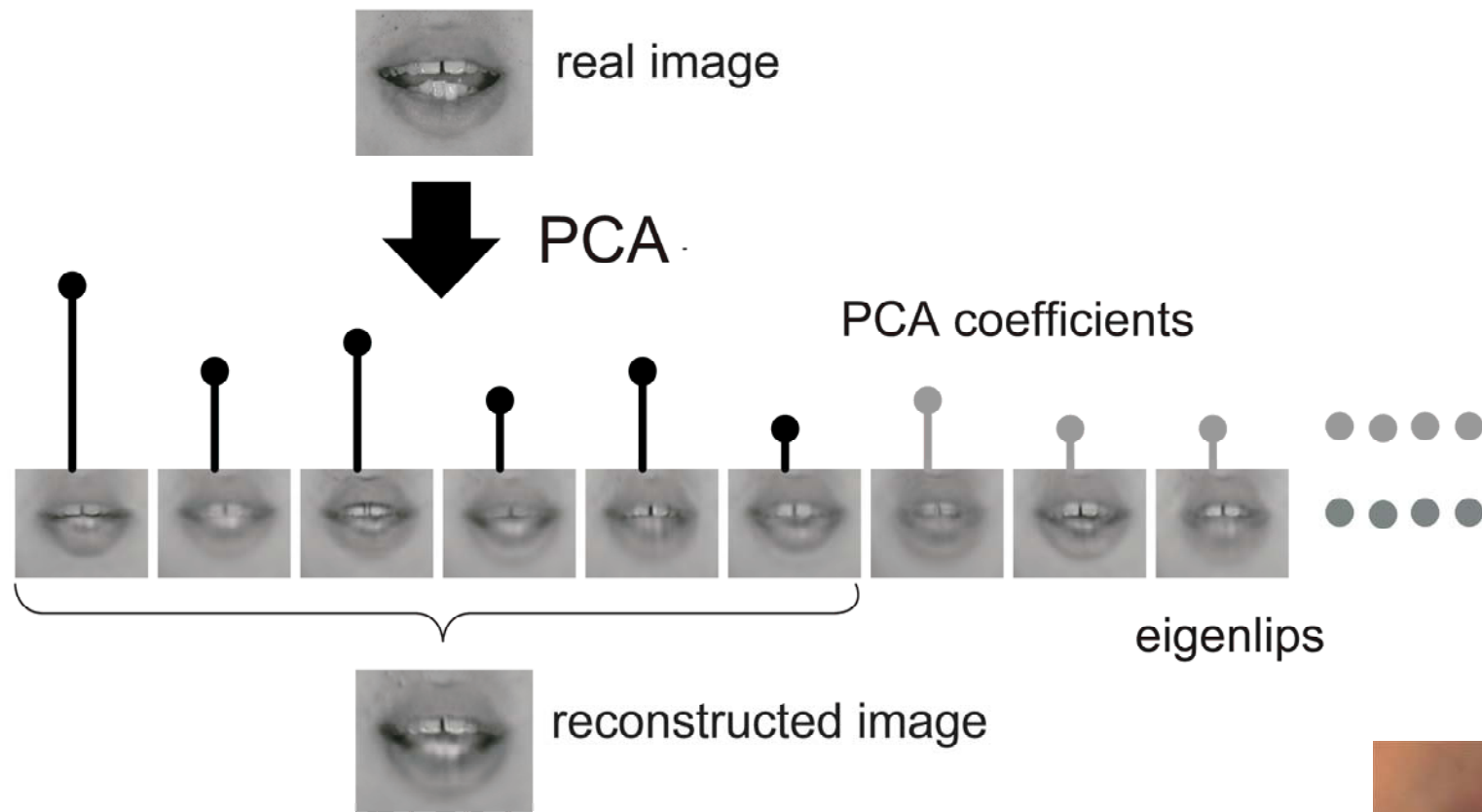
- Japanese 🗣️🗣️
- American English 🗣️🗣️🗣️🗣️🗣️🗣️
- Chinese (Mandarin) (by ATR) 🗣️
- Brazilian Portuguese (by Nitech, and UFRJ) 🗣️
- European Portuguese (by Nitech, Univ of Porto, and UFRJ) 🗣️
- Slovenian (by Bostjan Vesnicher, University of Ljubljana, Slovenia ) 🗣️
- Swedish (by Anders Lundgren, KTH, Sweden) 🗣️🗣️
- German (by University of Bonn, and Nitech) 🗣️
- Korean (by Sang-Jin Kim, ETRI, Korea) 🗣️🗣️
- Polish, Slovak, Finnish, Arabic, Farsi, Polyglot, etc.

Latest system

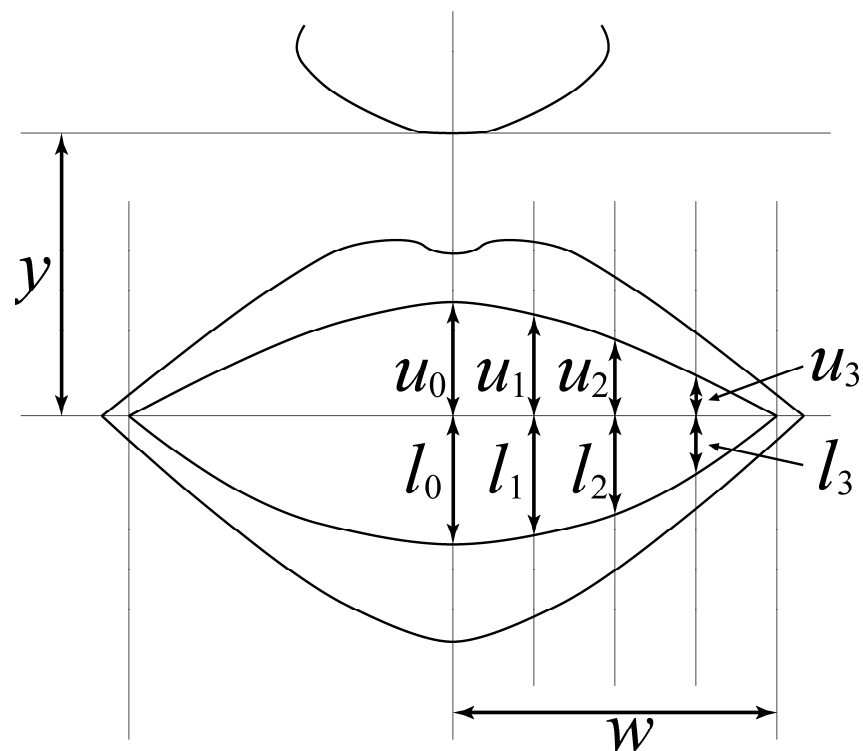
# Singing Voice Synthesis



# Audio-Visual Speech Synthesis (Pixel-based)



# Audio-Visual Speech Synthesis (Model-based)








[Click here](#) for a demo  
by Tamura, et al., Titech,  
Eurospeech99

# Human Motion Synthesis and Others

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[Click here](#) for various demos  
by Prof Kobayashi's group at Titech

# Small-Foot Print Synthesizer

- Acoustic model size < 100KB
- 0.1 Real Time
- Sample 1 
- Sample 2 
- Sample 3 
- Sample 4 
- Sample 5 

# In A Dialog System

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- **User:** 「バーカ!」 "You Fool!"
- **Agent:** 「何よ！馬鹿って言う方が馬鹿なのよ!」  
"What? Who slanders others is a real fool!"



# Summary

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## **HMM-based Approach to Flexible Speech Synthesis**

- ❑ Simultaneous modeling of spectrum, F0, and duration
- ❑ Provide flexibility: various voices, speaking styles, emotional expressions, etc.

A tool for constructing spoken dialogue systems