



Acoustic Modeling for Speech Synthesis

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Outline

Background

HMM-based acoustic modeling

- Training & synthesis

- Limitations

ANN-based acoustic modeling

- Feedforward NN

- RNN

Conclusion



Text-to-speech as sequence-to-sequence mapping

Automatic speech recognition (ASR)

Speech (real-valued time series) \rightarrow Text (discrete symbol sequence)

Statistical machine translation (SMT)

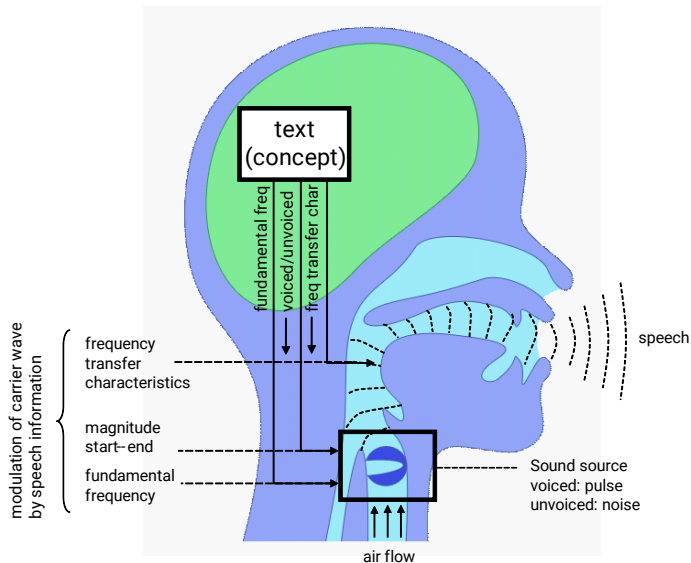
Text (discrete symbol sequence) \rightarrow Text (discrete symbol sequence)

Text-to-speech synthesis (TTS)

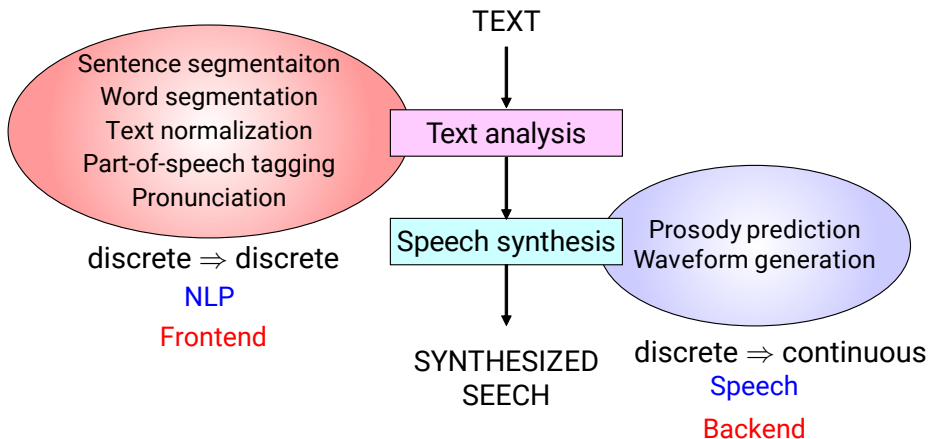
Text (discrete symbol sequence) \rightarrow Speech (real-valued time series)



Speech production process



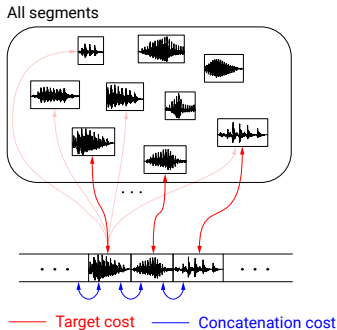
Typical flow of TTS system



This presentation mainly talks about backend



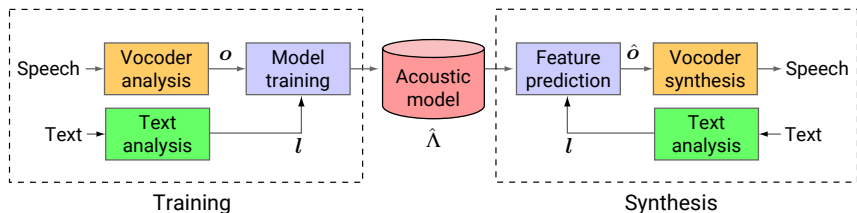
Concatenative speech synthesis



- Concatenate actual small speech segments from database
→ **Very high segmental naturalness**
- Single segment per unit (e.g., diphone) → diphone synthesis [1]
- Multiple segments per unit → unit selection synthesis [2]



Statistical parametric speech synthesis (SPSS) [4]

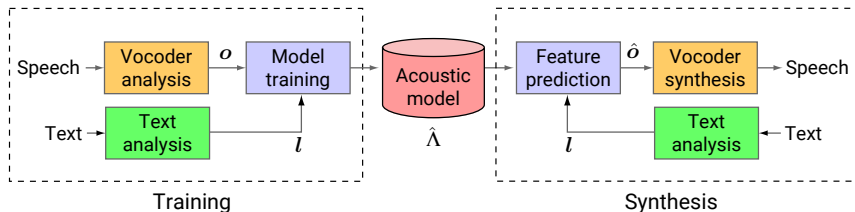


- Parametric representation rather than waveform
- Model relationship between linguistic & acoustic features
- Predict acoustic features then reconstruct waveform

SPSS can use any acoustic model, but HMM-based one is very popular
→ [HMM-based speech synthesis \[3\]](#)



Statistical parametric speech synthesis (SPSS) [4]



Pros

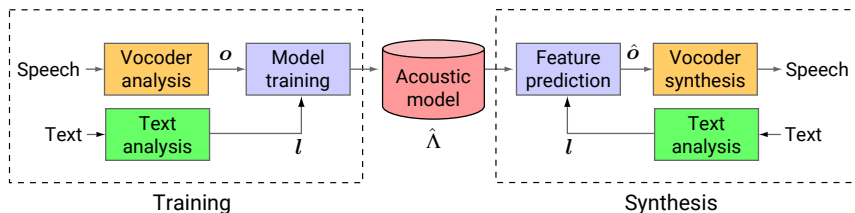
- Small footprint
- Flexibility to change voice characteristics
- Robust to data sparsity and noise/mistakes in data

Cons

- Segmental naturalness



Major factors for naturalness degradation



- **Vocoder analysis/synthesis**
 - *How to parameterize speech?*
- **Acoustic model**
 - *How to represent relationship between speech & text?*
- **Oversmoothing**
 - *How to generate speech from model?*



Formulation of SPSS

Training

- Extract linguistic features l & acoustic features o
- Train acoustic model Λ given (o, l)

$$\hat{\Lambda} = \arg \max_{\Lambda} p(o | l, \Lambda)$$

Synthesis

- Extract l from text to be synthesized
- Generate most probable o from $\hat{\Lambda}$ then reconstruct waveform

$$\hat{o} = \arg \max_o p(o | l, \hat{\Lambda})$$



Formulation of SPSS

Training

- Extract linguistic features l & acoustic features o
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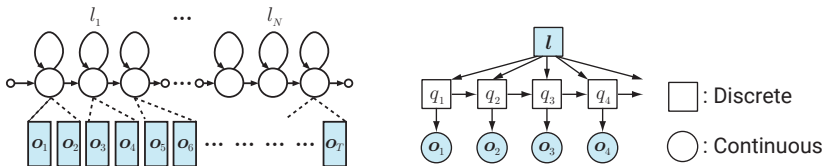
Synthesis

- Extract l from text to be synthesized
- Generate most probable o from $\hat{\Lambda}$ then reconstruct waveform


$$\hat{o} = \arg \max_o p(o | l, \hat{\Lambda})$$



Training – HMM-based acoustic modeling



$$\begin{aligned}
 p(\mathbf{o} \mid \mathbf{l}, \Lambda) &= \sum_{\forall \mathbf{q}} p(\mathbf{o} \mid \mathbf{q}, \Lambda) P(\mathbf{q} \mid \mathbf{l}, \Lambda) \quad \mathbf{q}: \text{hidden states} \\
 &= \sum_{\forall \mathbf{q}} \prod_{t=1}^T p(\mathbf{o}_t \mid q_t, \Lambda) P(\mathbf{q} \mid \mathbf{l}, \Lambda) \quad q_t: \text{hidden state at } t \\
 &= \sum_{\forall \mathbf{q}} \prod_{t=1}^T \mathcal{N}(\mathbf{o}_t; \boldsymbol{\mu}_{q_t}, \boldsymbol{\Sigma}_{q_t}) P(\mathbf{q} \mid \mathbf{l}, \Lambda)
 \end{aligned}$$

ML estimation of HMM parameters → Baum-Welch (EM) algorithm [5] 

Training – Linguistic features

Linguistic features: phonetic, grammatical, & prosodic features

- **Phoneme**

phoneme identity, position

- **Syllable**

length, accent, stress, tone, vowel, position

- **Word**

length, POS, grammar, prominence, emphasis, position, pitch accent

- **Phrase**

length, type, position, intonation

- **Sentence**

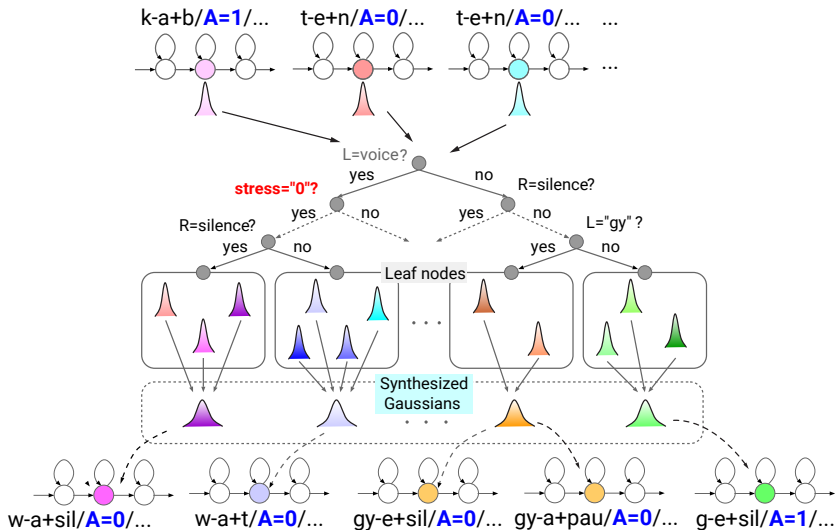
length, type, position

...

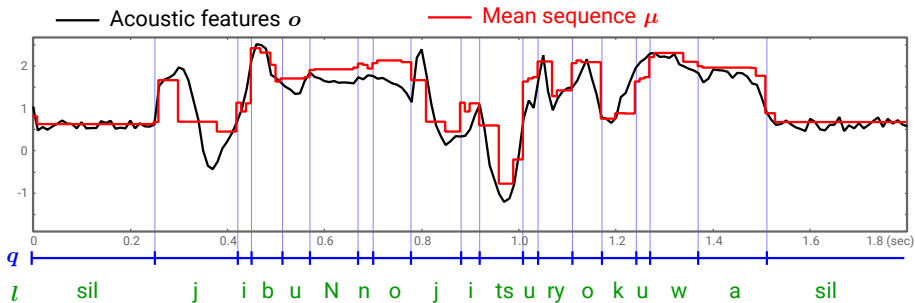
→ Impossible to have enough data to cover all combinations



Training – ML decision tree-based state clustering [6]



Training – Example



Formulation of SPSS

Training

- Extract linguistic features l & acoustic features o
- Train acoustic model Λ given (o, l)

$$\hat{\Lambda} = \arg \max_{\Lambda} p(o | l, \Lambda)$$

Synthesis

- Extract l from text to be synthesized
- Generate most probable o from $\hat{\Lambda}$ then reconstruct waveform

$$\hat{o} = \arg \max_o p(o | l, \hat{\Lambda})$$

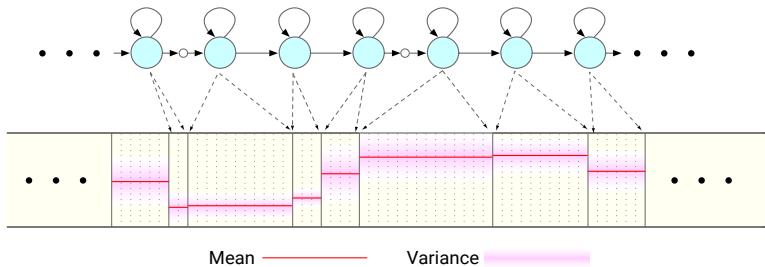


Synthesis – Predict most probable acoustic features

$$\begin{aligned}\hat{o} &= \arg \max_{\mathbf{o}} p(\mathbf{o} | \mathbf{l}, \hat{\Lambda}) \\ &= \arg \max_{\mathbf{o}} \sum_{\forall \mathbf{q}} p(\mathbf{o}, \mathbf{q} | \mathbf{l}, \hat{\Lambda}) \\ &\approx \arg \max_{\mathbf{o}} \max_{\mathbf{q}} p(\mathbf{o}, \mathbf{q} | \mathbf{l}, \hat{\Lambda}) \\ &= \arg \max_{\mathbf{o}} \max_{\mathbf{q}} p(\mathbf{o} | \mathbf{q}, \hat{\Lambda}) P(\mathbf{q} | \mathbf{l}, \hat{\Lambda}) \\ &\approx \arg \max_{\mathbf{o}} p(\mathbf{o} | \hat{\mathbf{q}}, \hat{\Lambda}) \quad s.t. \quad \hat{\mathbf{q}} = \arg \max_{\mathbf{q}} P(\mathbf{q} | \mathbf{l}, \hat{\Lambda}) \\ &= \arg \max_{\mathbf{o}} \mathcal{N}(\mathbf{o}; \boldsymbol{\mu}_{\hat{\mathbf{q}}}, \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}) \\ &= \boldsymbol{\mu}_{\hat{\mathbf{q}}} \\ &= \left[\boldsymbol{\mu}_{\hat{q}_1}^\top, \dots, \boldsymbol{\mu}_{\hat{q}_T}^\top \right]^\top\end{aligned}$$



Synthesis – Most probable acoustic features given HMM



\hat{o} → step-wise → discontinuity can be perceived



Synthesis – Using dynamic feature constraints [7]

$$o_t = \begin{bmatrix} c_t^\top & \Delta c_t^\top \end{bmatrix}^\top$$

$\left(\begin{array}{c} \text{blue box} \\ \text{red box} \end{array} \right)_{2M}$
 $\left(\text{blue box} \right)_M$
 $\left(\text{red box} \right)_M$

$$\Delta c_t = c_t - c_{t-1}$$

$$\begin{array}{c}
 o \\
 \vdots \\
 o_{t-1} \\
 \begin{array}{c} c_{t-1} \\ \Delta c_{t-1} \end{array} \\
 o_t \\
 \begin{array}{c} c_t \\ \Delta c_t \end{array} \\
 o_{t+1} \\
 \begin{array}{c} c_{t+1} \\ \Delta c_{t+1} \end{array} \\
 \vdots
 \end{array}
 =
 \begin{array}{c}
 W \\
 \begin{bmatrix}
 \dots & \vdots & \vdots & \vdots & \vdots & \dots \\
 \dots & 0 & I & 0 & 0 & \dots \\
 \dots & -I & I & 0 & 0 & \dots \\
 \dots & 0 & 0 & I & 0 & \dots \\
 \dots & 0 & -I & I & 0 & \dots \\
 \dots & 0 & 0 & 0 & I & \dots \\
 \dots & 0 & 0 & -I & I & \dots \\
 \dots & \vdots & \vdots & \vdots & \vdots & \dots
 \end{bmatrix}
 \end{array}
 \begin{array}{c}
 c \\
 \vdots \\
 c_{t-2} \\
 c_{t-1} \\
 c_t \\
 c_{t+1} \\
 \vdots
 \end{array}$$



Synthesis – Speech parameter generation algorithm [7]

$$\hat{o} = \arg \max_{\mathbf{o}} p(\mathbf{o} | \hat{\mathbf{q}}, \hat{\Lambda}) \quad s.t. \quad \mathbf{o} = \mathbf{W}\mathbf{c}$$

$$\hat{\mathbf{c}} = \arg \max_{\mathbf{c}} \mathcal{N}(\mathbf{W}\mathbf{c}; \boldsymbol{\mu}_{\hat{\mathbf{q}}}, \boldsymbol{\Sigma}_{\hat{\mathbf{q}}})$$

$$= \arg \max_{\mathbf{c}} \log \mathcal{N}(\mathbf{W}\mathbf{c}; \boldsymbol{\mu}_{\hat{\mathbf{q}}}, \boldsymbol{\Sigma}_{\hat{\mathbf{q}}})$$

$$\frac{\partial}{\partial \mathbf{c}} \log \mathcal{N}(\mathbf{W}\mathbf{c}; \boldsymbol{\mu}_{\hat{\mathbf{q}}}, \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}) \propto \mathbf{W}^\top \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}^{-1} \mathbf{W}\mathbf{c} - \mathbf{W}^\top \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}^{-1} \boldsymbol{\mu}_{\hat{\mathbf{q}}}$$

$$\mathbf{W}^\top \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}^{-1} \mathbf{W}\mathbf{c} = \mathbf{W}^\top \boldsymbol{\Sigma}_{\hat{\mathbf{q}}}^{-1} \boldsymbol{\mu}_{\hat{\mathbf{q}}}$$

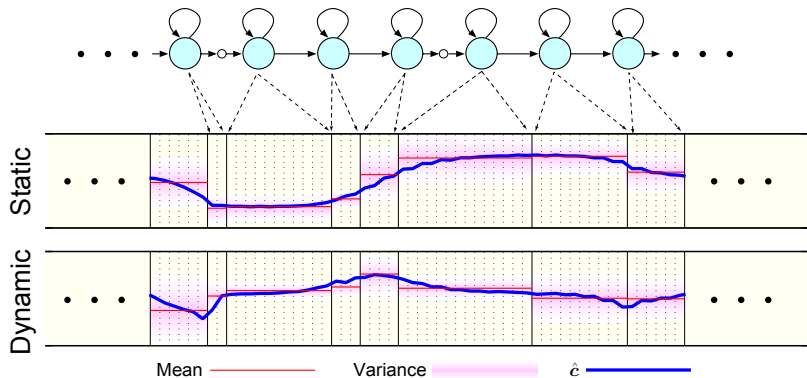
where

$$\boldsymbol{\mu}_{\mathbf{q}} = \left[\boldsymbol{\mu}_{q_1}^\top, \boldsymbol{\mu}_{q_2}^\top, \dots, \boldsymbol{\mu}_{q_T}^\top \right]^\top$$

$$\boldsymbol{\Sigma}_{\mathbf{q}} = \text{diag} [\boldsymbol{\Sigma}_{q_1}, \boldsymbol{\Sigma}_{q_2}, \dots, \boldsymbol{\Sigma}_{q_T}]$$

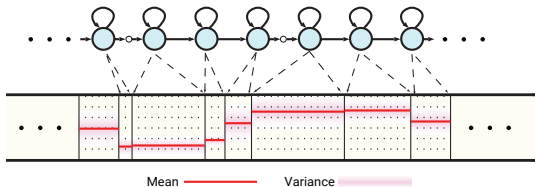
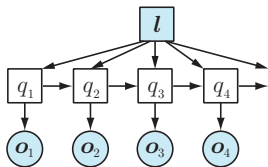


Synthesis – Most probable acoustic features under constraints between static & dynamic features



HMM-based acoustic model – Limitations (1)

Stepwise statistics

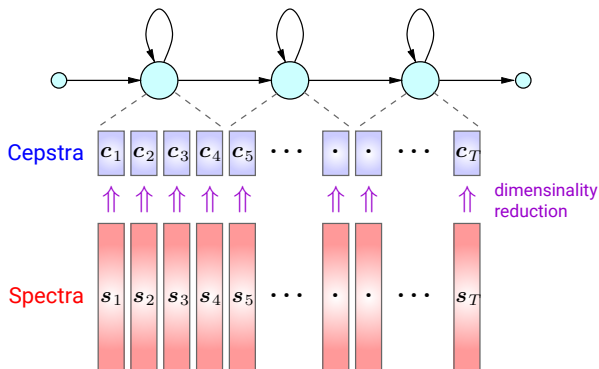


- Output probability only depends on the current state
- Within the same state, statistics are constant
→ **Step-wise statistics**
- Using dynamic feature constraints
→ **Ad hoc & introduces inconsistency betw. training & synthesis [8]**



HMM-based acoustic model – Limitations (2)

Difficulty to integrate feature extraction & modeling

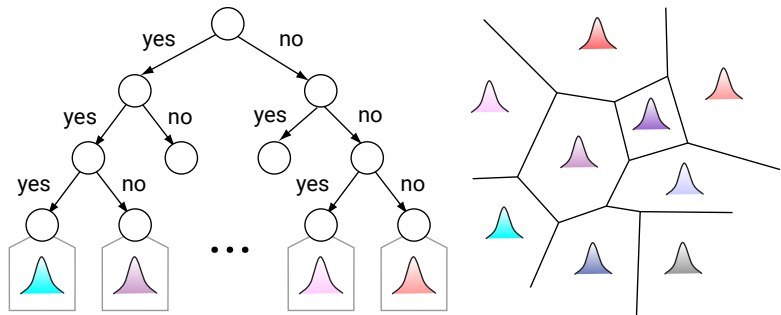


- Spectra or waveforms are high-dimensional & highly correlated
- Hard to be modeled by HMMs with Gaussian + diagonal covariance
→ Use low dimensional approximation (e.g., cepstra, LSPs)



HMM-based acoustic model – Limitations (3)

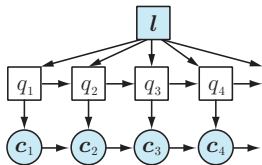
Data fragmentation



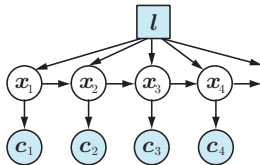
- Trees split input into clusters & put representative distributions
→ **Inefficient to represent dependency betw. ling. & acoust. feats.**
- Minor features are never used (e.g., word-level emphasis [9])
→ **Little or no effect**



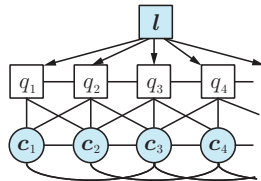
Alternatives – Stepwise statistics



ARHMM



LDM



Trajectory HMM

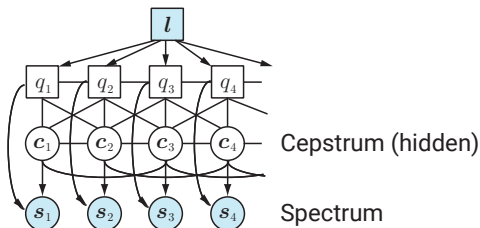
- Autoregressive HMMs (ARHMMs) [10]
- Linear dynamical models (LDMs) [11, 12]
- Trajectory HMMs [8]
- ...

Most of them use clustering → **Data fragmentation**

Often employ trees from HMM → **Sub-optimal**



Alternatives – Difficulty to integrate feature extraction



- Statistical vocoder [13]
- Minimum generation error with log spectral distortion [14]
- Waveform-level model [15]
- Mel-cepstral analysis-integrated HMM [16]

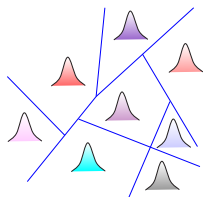
Use clustering to build tying structure → Data fragmentation

Often employ trees from HMM → Sub-optimal

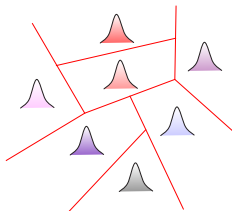


Alternatives – Data fragmentation

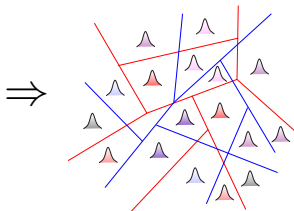
Tree1 (8 classes)



Tree2 (7 classes)



Combined (17 classes)



- Factorized decision tree [9, 17]
- Product of experts [18]

Each tree/expert still has data fragmentation → **Data fragmentation**
Fix other trees while building one tree [19, 20] → **Sub-optimal**



Linguistic → Acoustic mapping

- **Training**
Learn relationship between linguistic & acoustic features
- **Synthesis**
Map linguistic features to acoustic ones
- **Linguistic features used in SPSS**
 - Phoneme, syllable, word, phrase, utterance-level features
 - Around 50 different types
 - Sparse & correlated

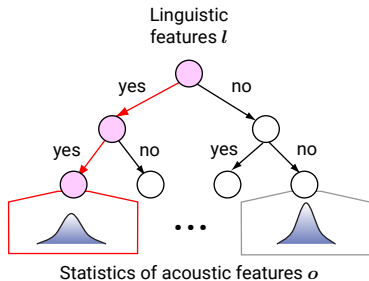
Effective modeling is essential



Decision tree-based acoustic model

HMM-based acoustic model & alternatives

→ Actually decision tree-based acoustic model



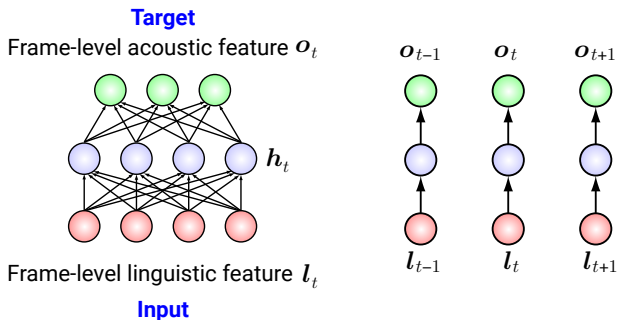
Regression tree: linguistic features → Stats. of acoustic features

Replace the tree with a general-purpose regression model

→ **Artificial neural network**



ANN-based acoustic model [21] – Overview



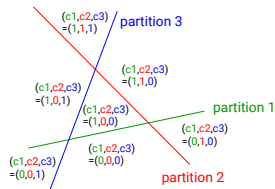
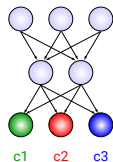
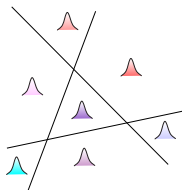
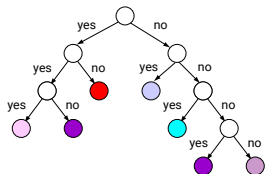
$$h_t = f(\mathbf{W}_{hl}l_t + \mathbf{b}_h) \quad \hat{\mathbf{o}}_t = \mathbf{W}_{oh}h_t + \mathbf{b}_o$$
$$\hat{\Lambda} = \arg \min_{\Lambda} \sum_t \|\mathbf{o}_t - \hat{\mathbf{o}}_t\|_2 \quad \Lambda = \{\mathbf{W}_{hl}, \mathbf{W}_{oh}, \mathbf{b}_h, \mathbf{b}_o\}$$

$\hat{\mathbf{o}}_t \approx \mathbb{E}[\mathbf{o}_t | l_t] \rightarrow$ Replace decision trees & Gaussian distributions



ANN-based acoustic model [21] – Motivation (1)

Distributed representation [22, 23]

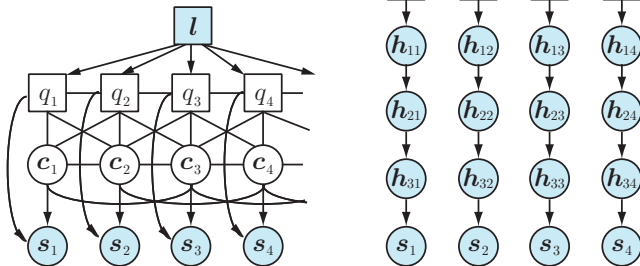


- **Fragmented:** n terminal nodes $\rightarrow n$ classes (linear)
- **Distributed:** n binary units $\rightarrow 2^n$ classes (exponential)
- **Minor features** (e.g., word-level emphasis) can affect synthesis



ANN-based acoustic model [21] – Motivation (2)

Integrate feature extraction [24, 25, 26]

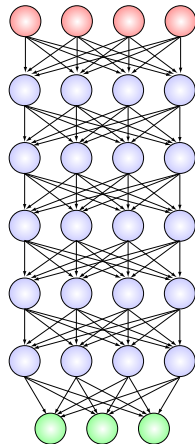
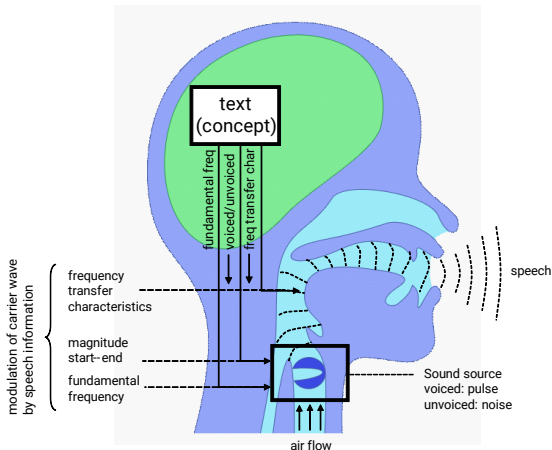


- Layered architecture with non-linear operations
- Can model high-dimensional/correlated linguistic/acoustic features
→ Feature extraction can be embedded in model itself



ANN-based acoustic model [21] – Motivation (3)

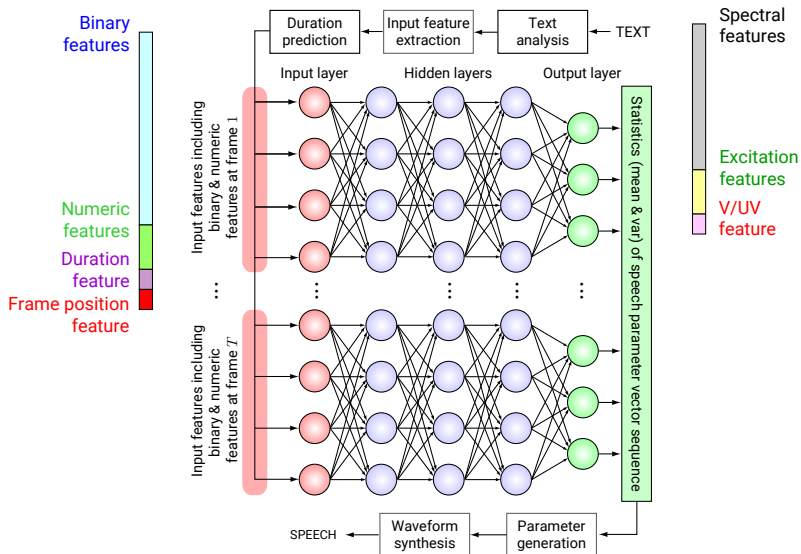
Implicitly mimic layered hierarchical structure in speech production



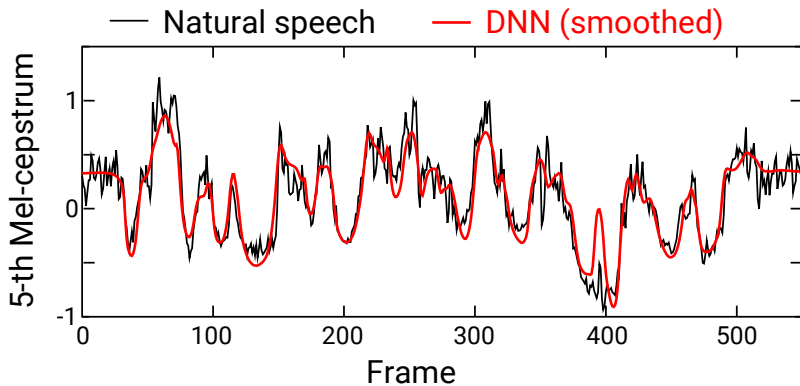
Concept → Linguistic → Articulator → Vocal tract → Waveform



DNN-based speech synthesis [21] – Implementation



DNN-based speech synthesis [21] – Example



DNN-based speech synthesis [21] – Subjective eval.

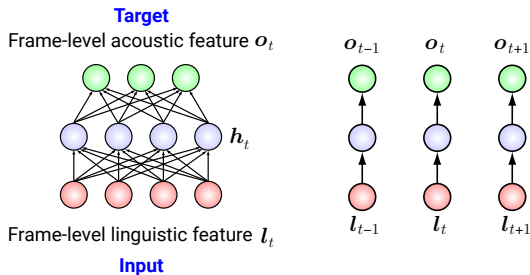
Compared HMM- & DNN-based TTS w/ similar # of parameters

- US English, professional speaker, 30 hours of speech data
- Preference test
- 173 test sentences, 5 subjects per pair
- Up to 30 pairs per subject
- Crowd-sourced

Preference scores (%)			
HMM	DNN	No pref.	#layers × #units
15.8	38.5	45.7	4 × 256
16.1	27.2	56.7	4 × 512
12.7	36.6	50.7	4 × 1024



Feedforward NN-based acoustic model – Limitation



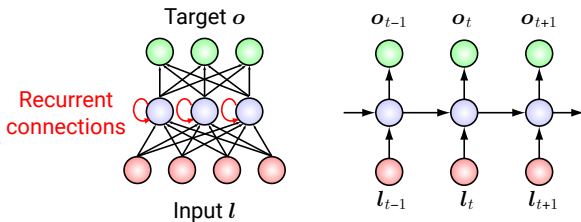
Each frame is mapped independently → **Smoothing is still essential**

Preference scores (%)		
DNN with dyn	DNN without dyn	No pref.
67.8	12.0	20.0

Recurrent connections → **Recurrent NN (RNN) [27]**



RNN-based acoustic model [28, 29]

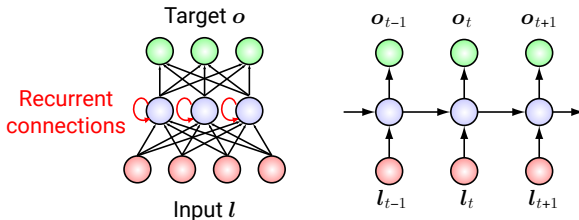


$$h_t = f(W_{hl}l_t + W_{hh}h_{t-1} + b_h) \quad \hat{o}_t = W_{oh}h_t + b_o$$
$$\hat{\Lambda} = \arg \min_{\Lambda} \sum_t \|o_t - \hat{o}_t\|_2 \quad \Lambda = \{W_{hl}, W_{hh}, W_{oh}, b_h, b_o\}$$

- DNN: $\hat{o}_t \approx \mathbb{E}[o_t | l_t]$
- RNN: $\hat{o}_t \approx \mathbb{E}[o_t | l_1, \dots, l_t]$



RNN-based acoustic model [28, 29]



- Only able to use previous contexts
 - Bidirectional RNN [27]: $\hat{o}_t \approx \mathbb{E}[o_t | l_1, \dots, l_T]$
- Trouble accessing long-range contexts
 - Information in hidden layers loops quickly decays over time
 - Prone to being overwritten by new information from inputs
 - Long short-term memory (LSTM) [30]



LSTM-RNN-based acoustic model [29]

Subjective preference test (same US English data)

DNN: 3 layers, 1024 units

LSTM: 1 layer, 256 LSTM units

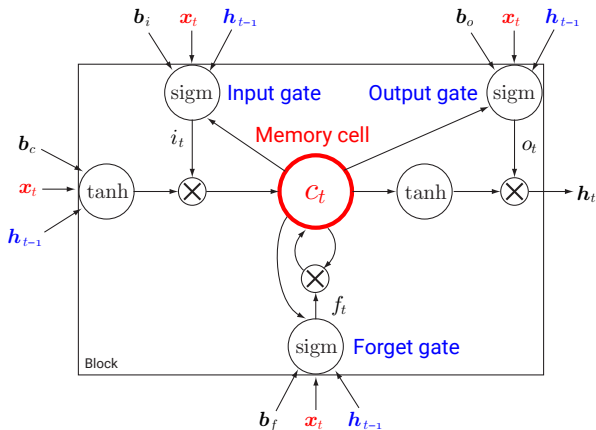
DNN with dyn	LSTM with dyn	No pref.
18.4	34.9	47.6

LSTM with dyn	LSTM without dyn	No pref.
21.0	12.2	66.8

→ Smoothing was still effective



Why?



Gate output: 0 -- 1

Input gate == 1
→ Write memory

Forget gate == 0
→ Reset memory

Output gate == 1
→ Read memory

- Gates in LSTM units: 0/1 switch controlling information flow
- Can produce rapid change in outputs
→ **Discontinuity**



How?

- Using loss function incorporating continuity
- Integrate smoothing → Recurrent output layer [29]

$$h_t = \text{LSTM}(l_t) \quad \hat{o}_t = W_{oh}h_t + W_{oo}\hat{o}_{t-1} + b_o$$

Works pretty well

LSTM with dyn (Feedforward)	LSTM without dyn (Recurrent)	No pref.
21.8	21.0	57.2

Having two smoothing together doesn't work well → Oversmoothing?

LSTM with dyn (Recurrent)	LSTM without dyn (Recurrent)	No pref.
16.6	29.2	54.2



Low-latency TTS by unidirectional LSTM-RNN [29]

HMM / DNN

- Smoothing by dyn. needs to solve set of T linear equations

$$\mathbf{W}^\top \Sigma_{\hat{q}}^{-1} \mathbf{W} \mathbf{c} = \mathbf{W}^\top \Sigma_{\hat{q}}^{-1} \boldsymbol{\mu}_{\hat{q}} \quad T: \text{Utterance length}$$

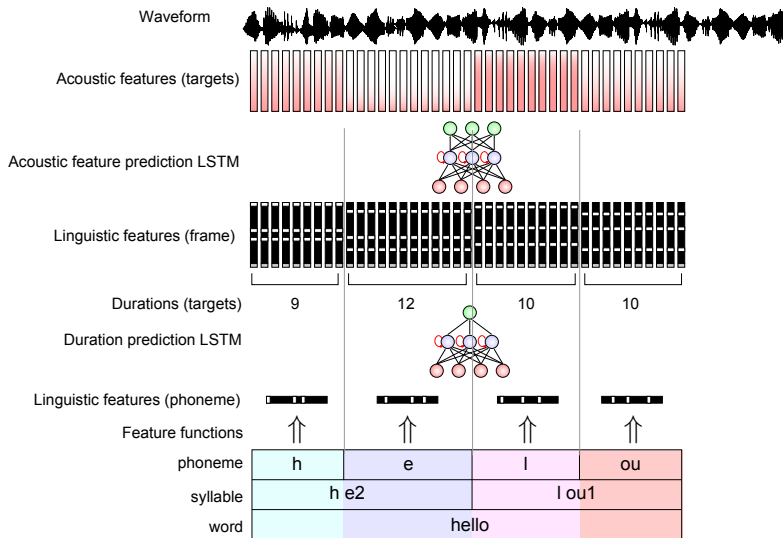
- Order of operations to determine the first frame c_1 (latency)
 - Cholesky decomposition [7] $\rightarrow \mathcal{O}(T)$
 - Recursive approximation [31] $\rightarrow \mathcal{O}(L)$ L : lookahead, $10 \sim 30$

Unidirectional LSTM with recurrent output layer [29]

- No smoothing required, fully time-synchronous w/o lookahead
- Order of latency $\rightarrow \mathcal{O}(1)$



Low-latency TTS by LSTM-RNN [29] – Implementation



Some comments

Is this new? . . . no

- Feedforward NN-based speech synthesis [32]
- RNN-based speech synthesis [33]

What's the difference?

- More layers, data, computational resources
- Better learning algorithm
- Modern SPSS techniques



Making LSTM-RNN-based TTS into production

Client-side (local) TTS for Android



Google Text-to-speech

Google Inc. Tools

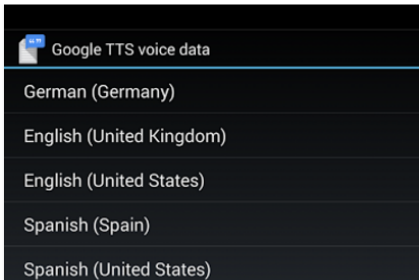
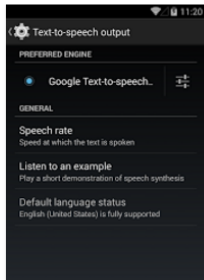
Top Developer

★★★★★ 546,569

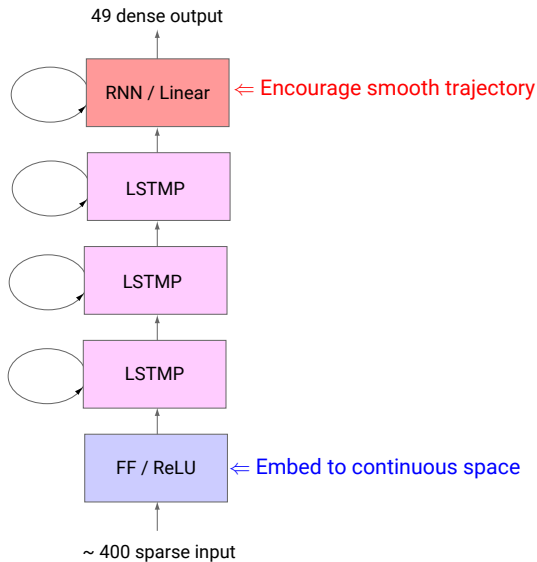
PEGI 3

This app is compatible with all of your devices.

Installed



Network architecture



Further optimization

- **Disk footprint**

HMM → 8-bit quantized [34]

RNN → Float

→ **Weight quantization**

- **Computational cost at inference**

HMM → Traversing decision trees (state) + parameter generation

RNN → Matrix-Vector multiplication (frame)

→ **Multi-frame inference**

- **Robustness**

HMM → “Soft” alignments using the Baum-Welch algorithm

RNN → Typically relies on fixed alignments [21]

→ **ϵ -contaminated Gaussian loss function**



Weight quantization

8-bit quantization of ANN weights to reduce footprint [35]

Language	Preference scores (%)		
	int8	float	No pref.
English (GB)	13.0	12.2	74.8
English (NA)	8.0	10.0	82.0
French	4.7	3.8	91.5
German	12.5	8.8	78.7
Italian	12.0	9.8	78.2
Spanish (ES)	8.8	7.5	83.7

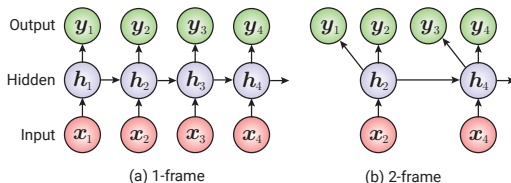
No degradation by weight quantization



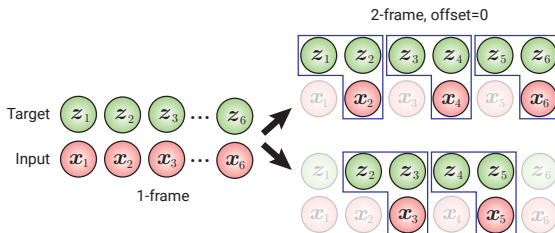
Multi-frame inference

Multi-frame inference

Bundle multiple targets to a single one [36]



Data augmentation



Multi-frame inference

4-frame inference w/ data augmentation

Language	Preference scores (%)		
	4-frame+	1-frame	No pref.
English (GB)	25.7	20.2	54.2
English (NA)	8.5	6.2	85.3
French	18.8	18.6	62.6
German	19.3	22.2	58.5
Italian	13.5	14.4	72.1
Spanish (ES)	12.8	17.0	70.3

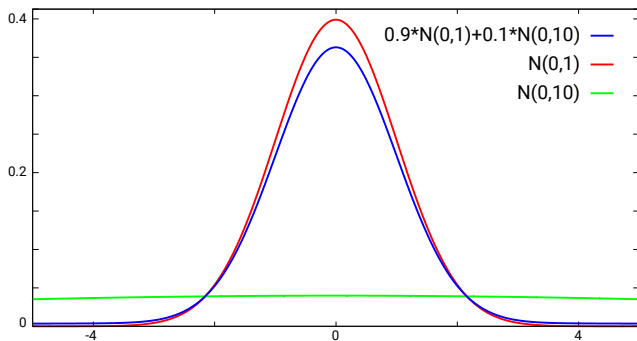
No degradation by multi-frame inference



ϵ -contaminated Gaussian loss

Use heavier-tailed distribution as loss

$$\mathcal{L}(z; \mathbf{x}, \Lambda) = -\log \{ (1 - \epsilon) \mathcal{N}(z; f(\mathbf{x}; \Lambda), \Sigma) + \epsilon \mathcal{N}(z; f(\mathbf{x}; \Lambda), c\Sigma) \}$$



ϵ -contaminated Gaussian loss

Language	Preference scores (%)		
	CG	L2	No pref.
English (GB)	27.4	18.1	54.5
English (NA)	7.6	6.8	85.6
French	24.6	15.9	59.5
German	17.1	20.8	62.1
Italian	16.0	10.6	73.4
Spanish (ES)	16.0	13.4	70.6



Comparison w/ HMM-based SPSS

- HMMs & LSTM-RNNs were quantized into 8-bit integers
- Same training data & text processing front-end
- Average disk footprint; **HMM: 1,560KB** **LSTM-RNN: 454.5KB**
- HMM: Time-recursive parameter generation [31] w/ 10-frame delay

Length	Latency (ms)		Total (ms)	
	LSTM	HMM	LSTM	HMM
character	12.5	19.5	49.8	49.6
word	14.6	25.3	61.2	80.5
sentence	31.4	55.4	257.3	286.2
paragraph	64.1	117.7	2216.1	2400.8



Comparison w/ HMM-based SPSS

Language	Preference scores (%)		
	LSTM	HMM	No pref.
English (GB)	31.6	28.1	40.3
English (NA)	30.6	15.9	53.5
French	68.6	8.4	23.0
German	52.8	19.3	27.9
Italian	84.8	2.9	12.3
Spanish (ES)	72.6	10.6	16.8



Comparison w/ concatenative TTS

Language	LSTM	Hybrid	No pref.
Arabic	13.9	22.1	64.0
Cantonese	25.1	7.3	67.6
Danish	37.0	49.1	13.9
Dutch	29.1	46.8	24.1
English (GB)	22.5	65.1	12.4
English (NA)	23.3	61.8	15.0
French	28.4	50.3	21.4
German	20.8	58.5	20.8
Greek	42.5	21.4	36.1
Hindi	42.5	36.4	21.1
Hungarian	56.5	30.3	13.3
Indonesian	18.9	57.8	23.4
Italian	28.1	49.0	22.9

Language	LSTM	Hybrid	No pref.
Japanese	47.4	28.8	23.9
Korean	40.6	25.8	33.5
Mandarin	48.6	17.5	33.9
Norwegian	54.1	30.8	15.1
Polish	14.6	75.3	10.1
Portuguese (BR)	31.4	37.8	30.9
Russian	26.7	49.1	24.3
Spanish (ES)	21.0	47.1	31.9
Spanish (NA)	22.5	55.6	21.9
Swedish	48.3	33.6	18.1
Thai	71.3	8.8	20.0
Turkish	61.3	20.8	18.0
Vietnamese	30.8	30.8	38.5



Acoustic models for speech synthesis – Summary

- **HMM**
 - Discontinuity due to step-wise statistics
 - Difficult to integrate feature extraction
 - Fragmented representation
- **Feedforward NN**
 - Easier to integrate feature extraction
 - Distributed representation
 - Discontinuity due to frame-by-frame independent mapping
- **(LSTM) RNN**
 - Smooth → Low latency



Acoustic models for speech synthesis – Future topics

- **Visualization for debugging**

- Concatenative → Easy to debug
- HMM → Hard
- ANN → Harder

- **More flexible voice-based user interface**

- Concatenative → Record all possibilities
- HMM → Weak/rare signals (input) are often ignored
- ANN → Weak/rare signals can contribute

- **Fully integrate feature extraction**

- Current: Linguistic features → Acoustic features
- Goal: Character sequence → Speech waveform



Thanks!



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